

# Towards a "Synchronous Reactive" UML Profile?

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# Synchronous hypotheses

S/R stands for Synchronous Reactive

- Logical division of time into **instants**
- At each instant: execute a synchronous cycle (a **reaction**)
  - Acquisition
  - Compute (a **global** run-to-completion)
  - Actuate
- **Signals** are the unique support for communication

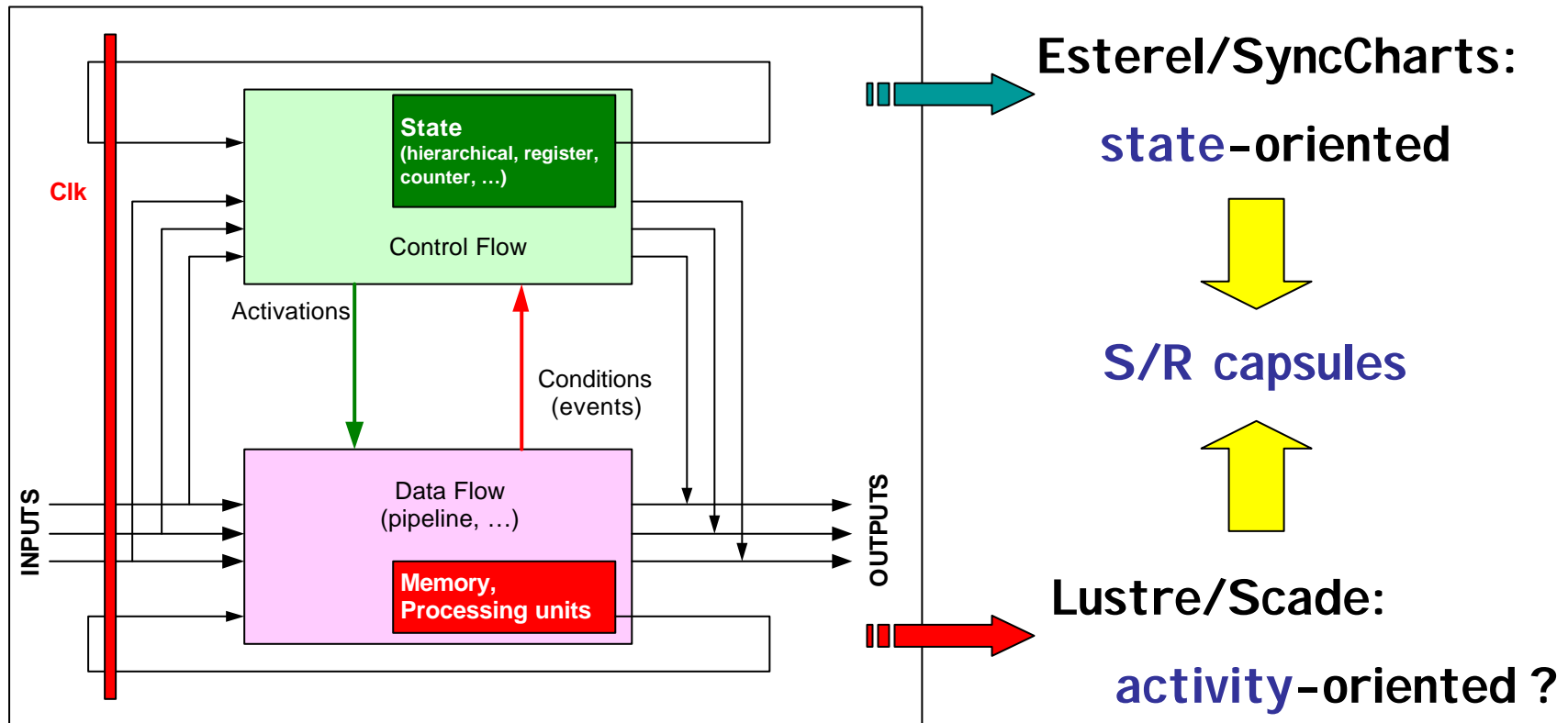
# Where S/R should be used

- Applications:
  - Embedded controller, HMI , HW/SW, ...
- Formalisms:
  - Strictly synchronous
    - SCADE, Esterel Studio, Block Diagrams
  - Almost synchronous
    - Statecharts, VHDL/Verilog, Simulink, Scicos

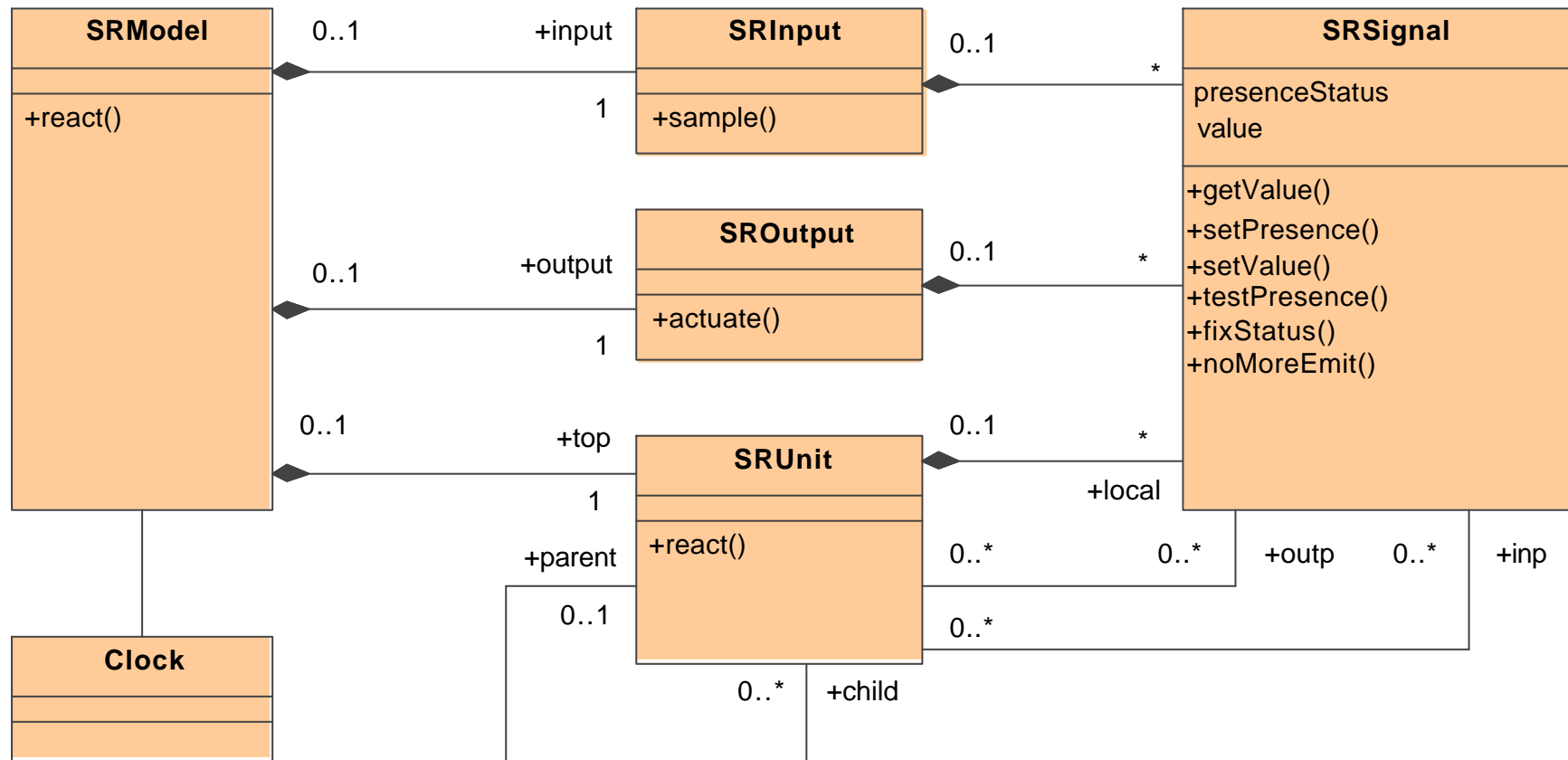


**Circuits CAD  
DSP, autom. Control  
simulators**

# Control-flow / Data-flow



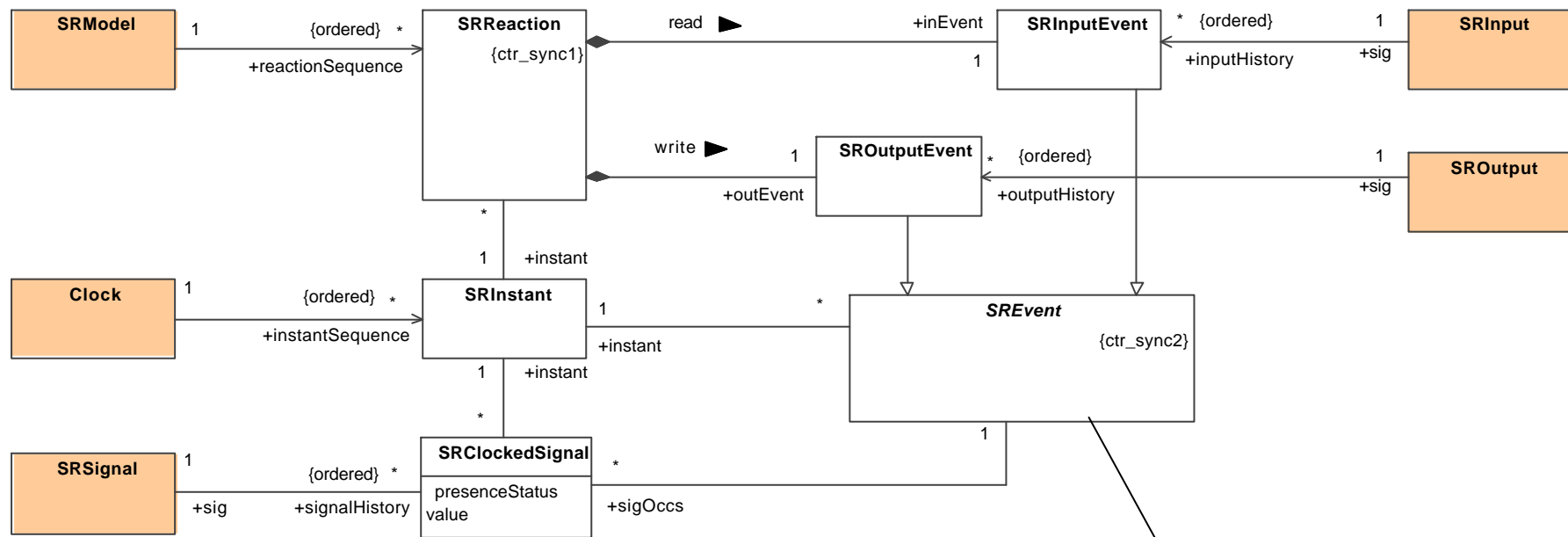
# S/R semantic domain



**Not a metamodel – Only to represent main concepts**

# Dynamic semantics

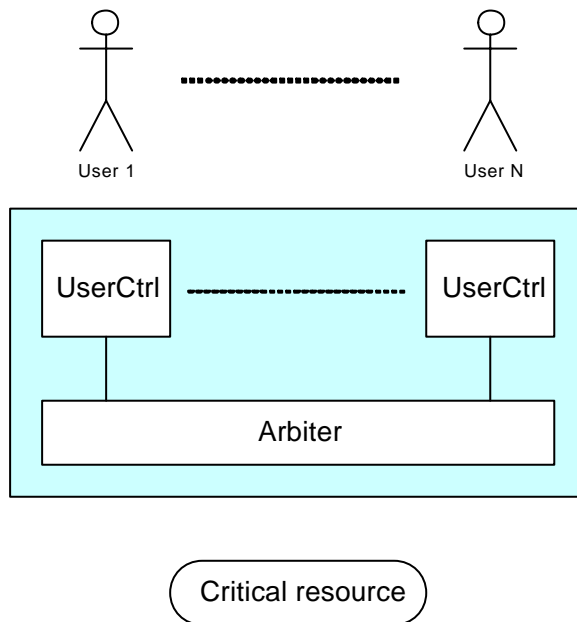
**Reaction =  
Behavior at  
one instant**



**Signal  
occurrence**

**Event =  
Set of  
signal  
occurrences**

# Example of an Arbiter

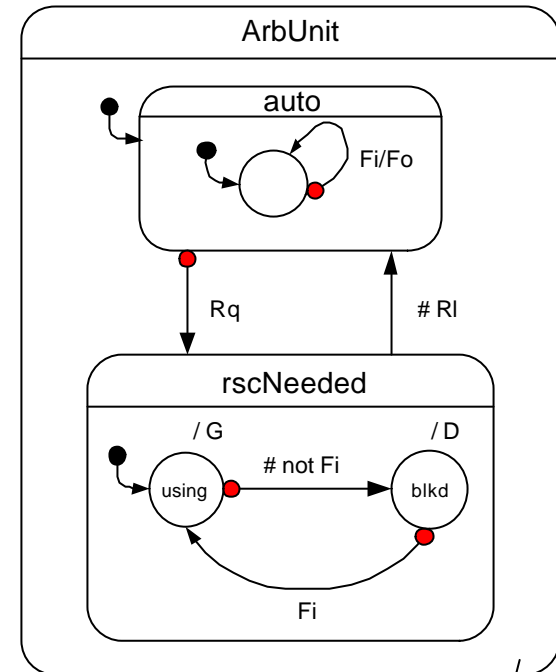
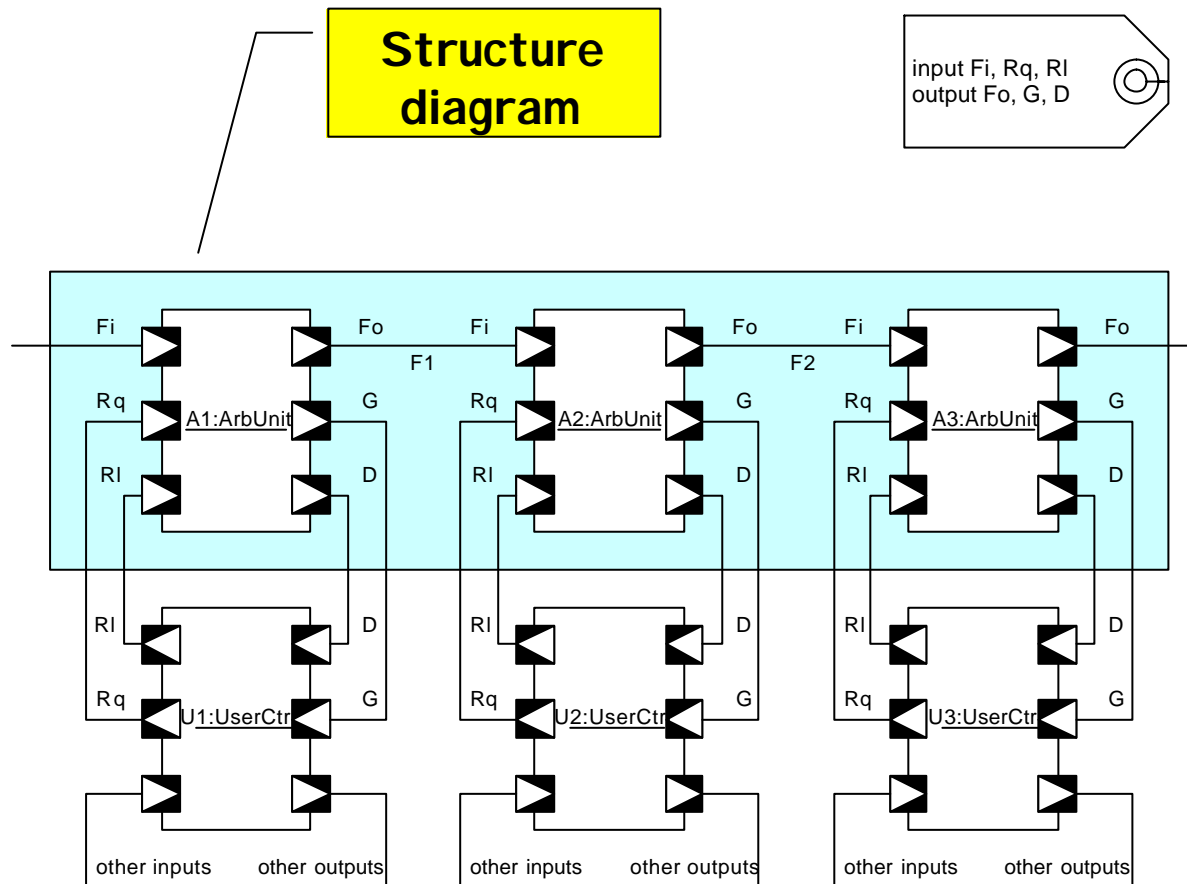


- Users: Rq and RI
- Arbiter: G, D
- Exclusive access
- Static priority
- D valued with the nb of candidates for the resource with higher priority
- Linear description vs. the nb of users

# State-based synchronous modeling

Structure  
diagram

input Fi, Rq, RI  
output Fo, G, D



syncCharts



# Limitations of the UML State Machines

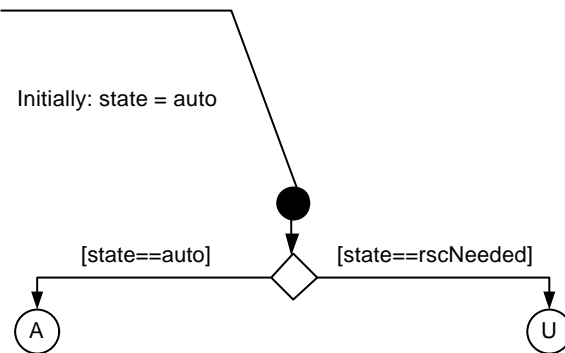
- Object-based variant of statecharts
- Semantics described in terms of operations of a hypothetical machine
- Event queue + dispatcher
- Events are dispatched and processed one at a time
- Run-to-completion assumption
- Poor support for concurrency

# What is missing

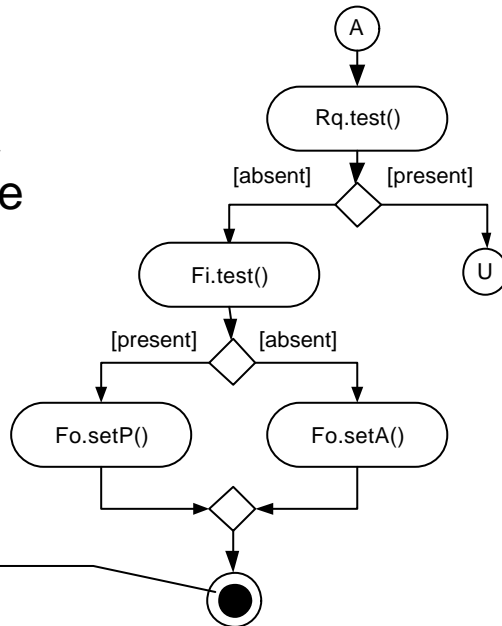
- Dealing with one event at a time is not acceptable for S/R models: **many** is the rule
- **Combination** of events (signals)
- Run-to-completion: too much restrictive. S/R have **high degree of concurrency**
- A notion out of the scope of classical asynchronous models: **reaction to the absence**
- Needs: **a clear notion of instant**

# Activity-oriented approach

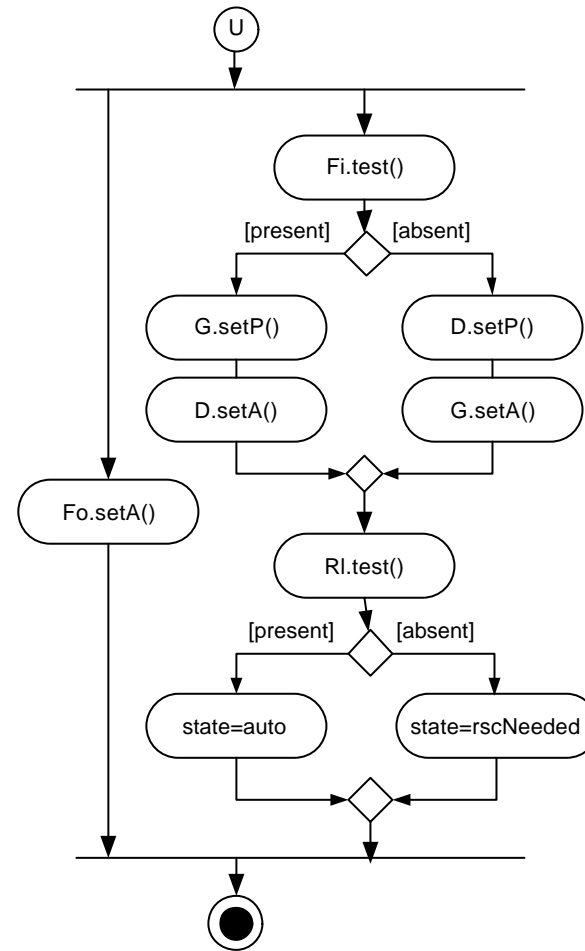
**Initial node**



Activity diagram for a reaction of the ArbUnit



**Final node**



Activities from initial to final  
**within one instant**

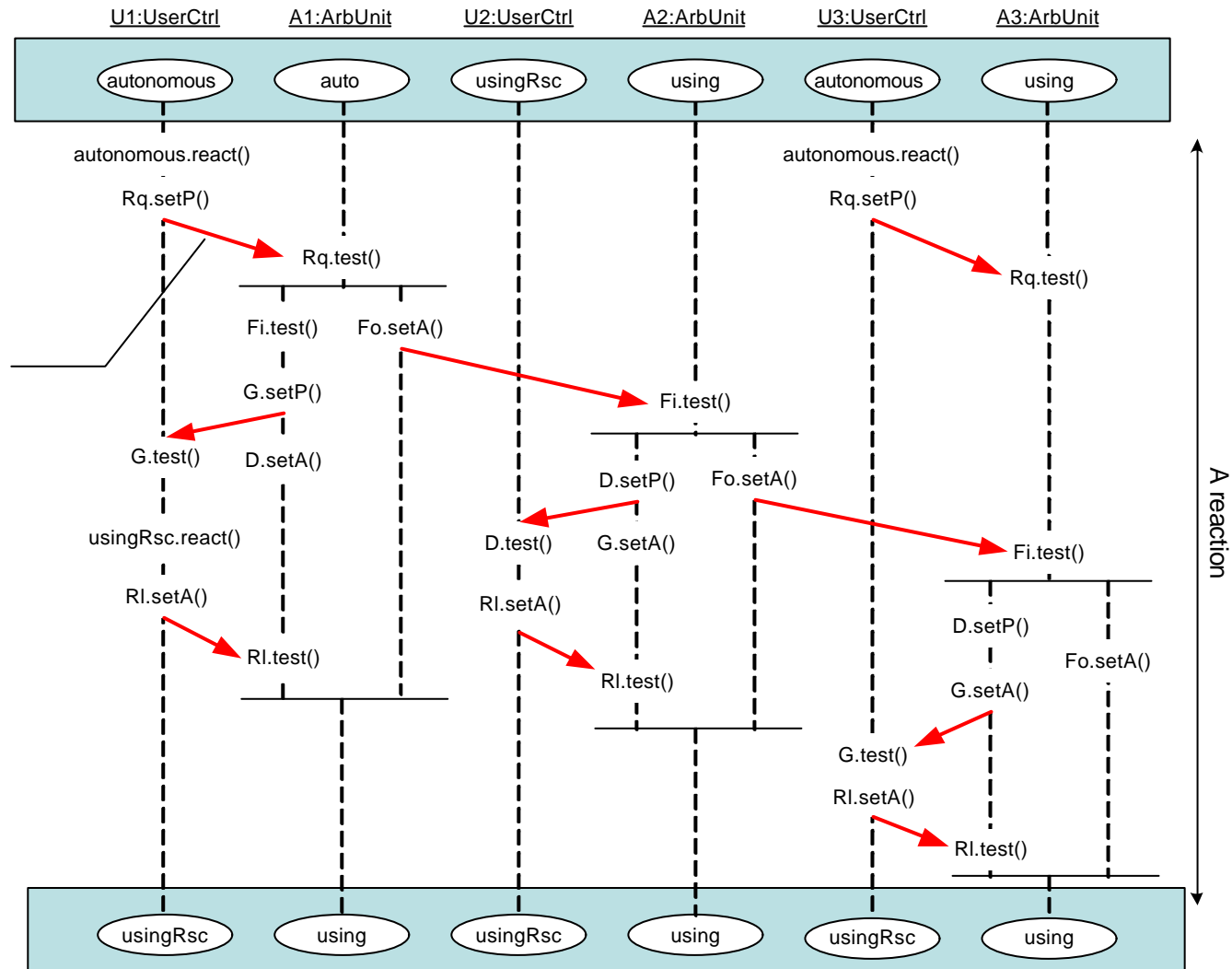
# Emergent behavior

# Finite and acyclic at each instant

# Causality relation

A signal may  
be tested  
only after  
being set

## Stable configuration



|         | SR   | SPT   |
|---------|--|---|
| Purpose | <p>High-level design &amp; programming</p> <p>Implementation independent</p>   | <p>Temporal analysis<br/>Performance analysis<br/>Real-time simulation</p> <p>Relevance of timing figures?</p>                    |
| Time    | <p>Logical discrete time</p> <p>abstract causality within instant</p> <p>Strict instant: possibility to lose fleeting events</p> | <p>Reference clock<br/>(represents physical time)</p> <p>Causality appears as time precedence</p> <p>Signal buffering, queues</p> |

# Scheduling in S/R

- Temporal and/or spatial mapping (SynDEx)
- Essential needs: **respect causality**
- Introduce chronometric time on architectural platform resources
- Often: a **uniform scheduling** for the whole application (i.e., a scheduling valid for all reactions).

# Conclusion

- “Control system engineering” has specific needs, not all addressed by the UML
- The S/R approach answers some of them
- UML + ...
- SPT OK for real-time cooperation of objects
- S/R well-suited for Control flow/Data flow tight interactions. But it demands relaxing some UML rules (especially for UML SM semantics)

# S/R Mixed Architecture

