

Software security, secure programming

Lecture 4: How to look at the binary level

Master M2 Cybersecurity & MoSiG

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Reminder

So far, we saw that:

- ▶ Unsecure softwares are (almost) everywhere ...
- ▶ Programming languages (often) contribute to produce unsecure software
- ▶ Looking at the source-level may not be enough
→ the **binary level** of the code matters, e.g.:
 - ▶ undefined behaviors + optimisations
 - ▶ memory layout
 - ▶ cache accesses
 - ▶ etc.

⇒ analysing the code level semantics is not sufficient for vulnerability detection and analysis ...

⇒ **need tool and technique to understand the executable code**

Outline

Reverse Engineering

Inspecting the binary code

Some demos ...

Software = several knowledge/information levels

- ▶ specifications, algorithms, data structures
- ▶ source code structure
objects, variables, types, functions, control and data flows (CFGs and DFGs)
- ▶ assembly and
- ▶ binary code (executable)
stack layout, optimizations,

Rk: \exists sometimes a **bytecode** level (Java, LLVM, etc.)

Reverse-engineering in practice:

- ▶ disassembling: binary \rightarrow assembly level
- ▶ de-compiling: binary \rightarrow source level
- ▶ source level \rightarrow model level ...

Reverse engineering a software - When ? (2)

- ▶ when the source code not/no longer available
 - ▶ updating, maintaining legacy code
 - ▶ analyzing COST, extern libraries
 - ▶ security (vulnerability, malware)
- ▶ when source code not sufficient enough

what you see is not what you execute [T. Reps]

optimization, memory layout, undefined behavior, protections, etc.

Rks

- ▶ source and/or binary code may be obfuscated ...
- ▶ in some situations need to consider only **memory dumps**

Memory layout at runtime (simplified)

Executable code = (binary) file produced by the compiler

→ need to be **loaded** in memory to be executed (using a *loader*)

However:

- ▶ no absolute addresses are stored in the executable code
→ decided at “load time”
- ▶ not all the executable code is stored in the executable file
(e.g., dynamic libraries)
- ▶ data memory can be dynamically allocated
- ▶ data can become code (and conversely ...)
- ▶ etc.

The executable file should contain all the information ...

∃ standards executable formats: ELF (Linux), PE (Windows), etc.

- ▶ header
- ▶ sections: text, initialized/uninitialized data, symbol tables, relocation tables, etc.

Rks: stripped (no symbol table) vs verbose (debug info) executables ...

x86 (32) assembly language in one slide

Registers:

- ▶ stack pointer (ESP), frame pointer (EBP), program counter (EIP)
- ▶ general purpose: EAX, EBX, ECX, EDX, ESI, EDI
- ▶ flags

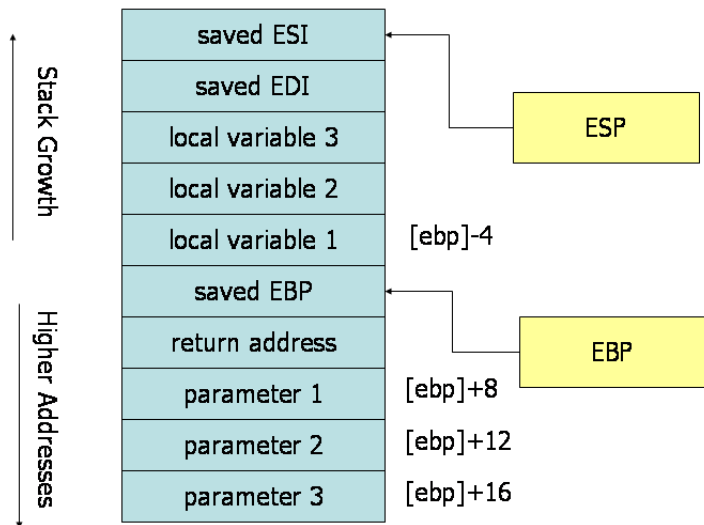
Instructions:

- ▶ data transfer (MOV), arithmetic (ADD, etc.)
- ▶ logic (AND, TEST, etc.)
- ▶ control transfer (JUMP, CALL, RET, etc)

Addressing modes:

- ▶ register: `mov eax, ebx`
- ▶ immediate: `mov eax, 1`
- ▶ direct memory: `mov eax, [esp+12]`

Stack layout for the x86 32-bits architecture



ABI (Application Binary Interface)

to “standardize” how processor resources should be used

⇒ required to ensure compatibilities at binary level

- ▶ sizes, layouts, and alignments of basic data types
- ▶ **calling conventions**
argument & return value passing, saved registers, etc.
- ▶ system calls to the operating system
- ▶ the binary format of object files, program libraries, etc.

	Cleans Stack	Arguments	Arg Ordering
cdecl	Caller	On the Stack	Right-to-left
fastcall	Callee	ECX,EDX, then stack	Left-to-Right
stdcall	Callee	On the Stack	Left-to-Right
VC++ thiscall	Callee	EDX (this), then stack	Right-to-left
GCC thiscall	Caller	On the Stack (this pointer first)	Right-to-left

Figure: some calling conventions

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Some demos ...

Understanding and analysing binary code ?

```
01010100 01101000
01101001 01101110
01101011 00100000
01100100 01101001
01100110 01100110
01100101 01110010
01100101 01101110
01110100 00101110
```

```
00000000
00000001
00000003
00000007
00000008
0000000C
0000000F
00000011
00000014
00000016
00000019
0000001B
0000001D
0000001F
00000022
00000025
```

```
push    ebp
mov     ebp, esp
movzx   ecx, [ebp+arg_0]
pop     ebp
movzx   dx, cl
lea     eax, [edx+edx]
add     eax, edx
shl     eax, 2
add     eax, edx
shr     eax, 8
sub     cl, al
shr     cl, 1
add     al, cl
shr     al, 5
movzx   eax, al
retn
```

Disassembling !

statically:

disassemble the **whole** file content **without executing it** ...

dynamically: disassemble the **current** instruction path **under execution/emulation** ...

Static disassembly

Recovering assembly-level code

- ▶ a non trivial task → static disassembling of x86 code **undecidable** (dynamic jumps, variable-length instructions, etc.)
main issue: distinguishing **code** vs **data** . . .
- ▶ several existing strategies (linear sweep, recursive disassembly, etc.)
- ▶ produce assembly-level IR instead of native assembly code
→ simpler language (a few instruction opcodes), explicit semantics (no side-effects), share analysis back-ends

Some existing tools

- ▶ IDA Pro
a well-known commercial disassembler, # useful features
- ▶ On Linux platforms (for ELF formats):
 - ▶ `objdump` (-S for code disassembling)
 - ▶ `readelf`

Static disassembly (cont'd)

See other slides available on the web page . . .

Dynamic disassembly

Main advantage: disassembling process **guided by** the execution

- ▶ ensures that instructions only are disassembled
- ▶ the whole execution context is available (registers, flags, addresses, etc.)
- ▶ dynamic jump destinations are resolved
- ▶ dynamic libraries are handled
- ▶ etc.

However:

- ▶ only a (small) part of the executable is disassembled
- ▶ need some suitable execution platform, e.g.:
 - ▶ emulation environment
 - ▶ binary level code instrumentation
 - ▶ (scriptable) debugger
 - ▶ etc.

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Reverse Engineering

Inspecting the binary code

Some demos ...