

Efficient Robust Monitoring for STL

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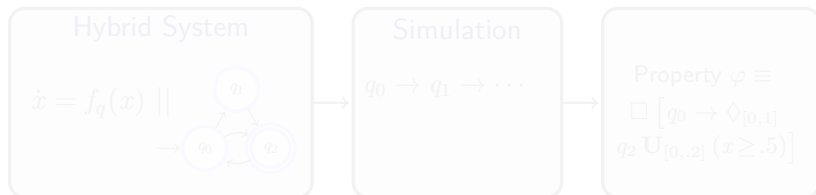
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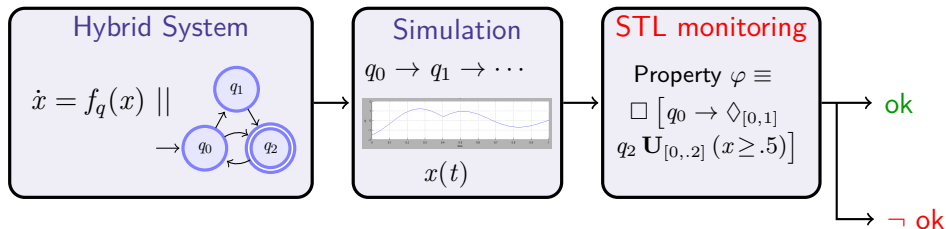
Overview

- ▶ **Signal Temporal Logic (STL):** temporal specifications for continuous and hybrid systems
- ▶ Quantitative satisfaction of STL can accommodate noise/approximation, increase coverage



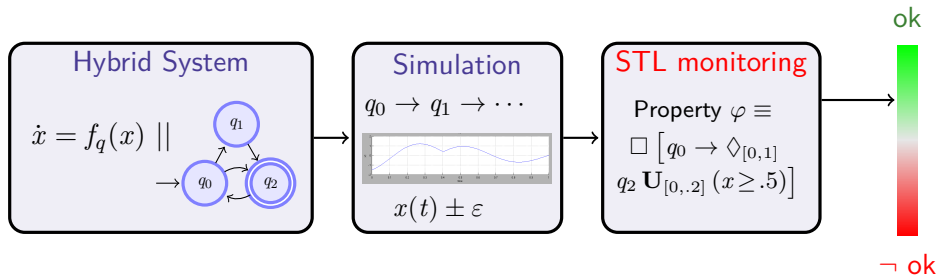
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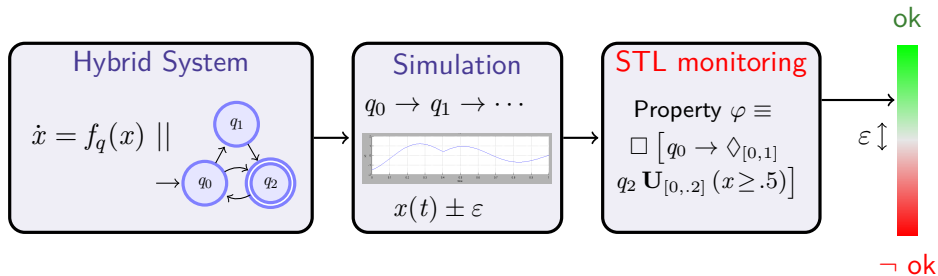
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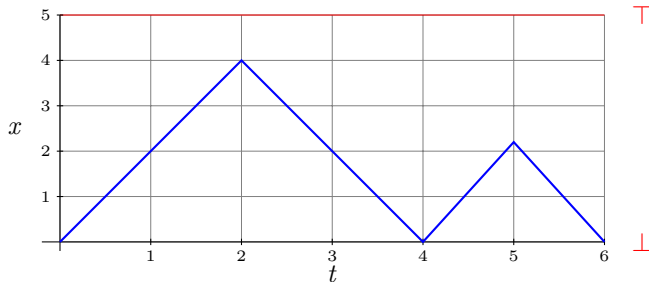
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Example: Boolean Monitoring



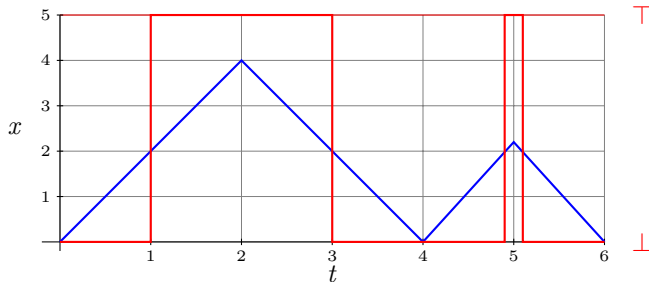
Satisfaction signal of :

▶ $\varphi = x \geq 2$

▶ $\varphi = \diamond_{[0,0.5]} (x \geq 2)$

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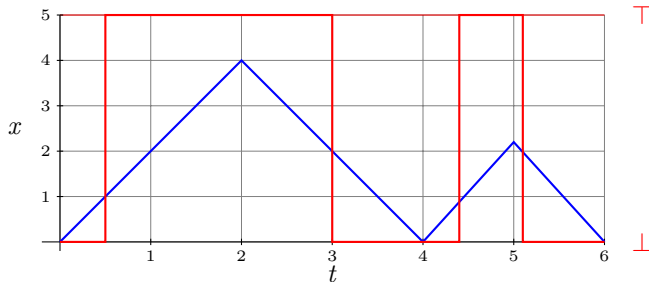
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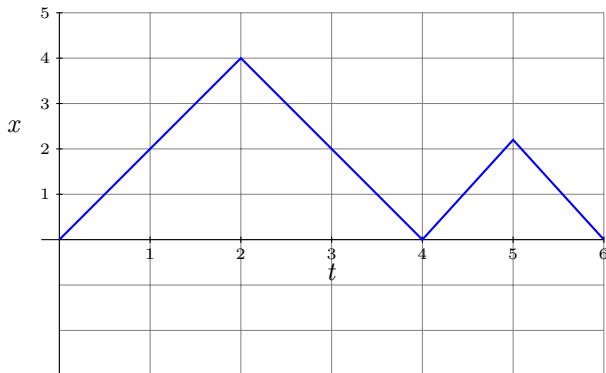
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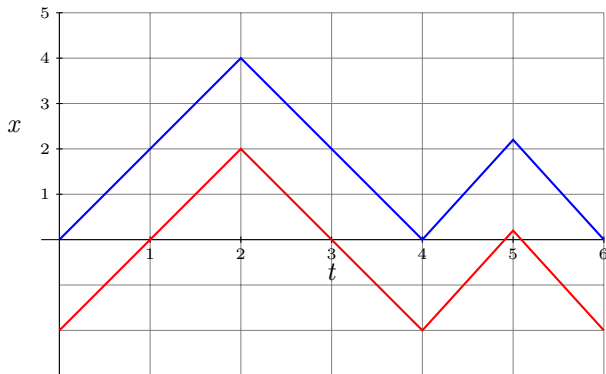
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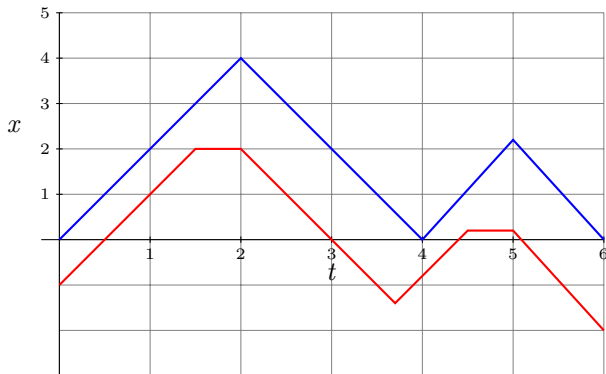
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Outline

- 1 Signal Temporal Logic
- 2 Robust Monitoring Algorithms
- 3 Complexity and Evaluation

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Formal Definitions

Definition (STL Syntax)

$$\varphi := \text{true} \mid x_i \geq c \mid \neg\varphi \mid \varphi \wedge \psi \mid \varphi \mathbf{U}_I \psi$$

with I closed interval of \mathbb{R}^+

Definition (STL Semantics)

The validity of a formula φ with respect to a trace w at time t is

$$w, t \models \text{true}$$

$$w, t \models x_i \geq c \iff x_i^w(t) \geq c$$

$$w, t \models \neg\varphi \iff w, t \not\models \varphi$$

$$w, t \models \varphi \wedge \psi \iff w, t \models \varphi \text{ and } w, t \models \psi$$

$$w, t \models \varphi \mathbf{U}_I \psi \iff \exists t' \in t + I \text{ s.t. } w, t' \models \psi \\ \text{and } \forall t'' \in [t, t'], w, t'' \models \varphi$$

Additionally: $\Diamond_I \varphi := \top \mathbf{U}_I \varphi$ and $\Box_I \varphi := \neg \Diamond_I \neg \varphi$.

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Additionally: $\diamond_I \varphi := \top \mathbf{U}_I \varphi$ and $\square_I \varphi := \neg \diamond_I \neg \varphi$.

Monitoring

Truth value of a formula for a given trace defines a Boolean signal

Definition (Satisfaction Signal)

$$\chi(\varphi, w, \cdot) := t \mapsto \begin{cases} \top & \text{if } w, t \models \varphi \\ \perp & \text{otherwise} \end{cases}$$

Procedure: by bottom-up computation of $\chi(\psi, x, \cdot)$ for each subformula $\psi \in \varphi$

From Boolean to quantitative semantics

Boolean algebra ($\{\top, \perp\}, <, -$)	Real algebra ($\mathbb{R} \cup \{\top, \perp\}, <, -$)
$p \vee p \sim p$	—
$p \wedge \text{true} \sim p$	—
$p \vee (q \wedge r) \sim (p \wedge q) \vee (p \wedge r)$	—
$\neg p \wedge \neg q \sim \neg(p \vee q)$	—
$p \vee \neg p \sim \text{true}$	x

Satisfaction Signal

$$\begin{aligned}\chi(\text{true}, w, t) &= \top \\ \chi(x_i \geq c, w, t) &= \begin{cases} \top & \text{if } x_i(t) \geq c, \\ \perp & \text{otherwise} \end{cases} \\ \chi(\neg\varphi, w, t) &= \neg\chi(\varphi, w, t) \\ \chi(\varphi \wedge \psi, w, t) &= \min\{\chi(\varphi, w, t), \chi(\psi, w, t)\} \\ \chi(\varphi \mathbf{U}_I \psi, w, t) &= \sup_{t' \in t+I} \min\{\chi(\psi, w, t'), \inf_{t'' \in [t, t']} \chi(\varphi, w, t'')\}\end{aligned}$$

Quantitative Semantics

$$\rho(\text{true}, w, t) = \top$$

$$\rho(x_i \geq c, w, t) = x_i(t) - c$$

$$\rho(\neg\varphi, w, t) = -\rho(\varphi, w, t)$$

$$\rho(\varphi \wedge \psi, w, t) = \min\{\rho(\varphi, w, t), \rho(\psi, w, t)\}$$

$$\rho(\varphi \mathbf{U}_I \psi, w, t) = \sup_{t' \in t+I} \min\{\rho(\psi, w, t'), \inf_{t'' \in [t, t']} \rho(\varphi, w, t'')\}$$

Property of Robustness Estimate

- ▶ Sign indicates satisfaction status
- ▶ Absolute value indicates tolerance

Theorem (Faneikos and Pappas 2009)

$$\begin{aligned} \rho(\varphi, w, t) > 0 &\Rightarrow w, t \models \varphi \\ w, t \models \varphi \text{ and } \|w - w'\|_\infty < \rho(\varphi, w, t) &\Rightarrow w', t \models \varphi \end{aligned}$$

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Corollary

$$\begin{aligned} \rho(\varphi, w, t) < 0 &\Rightarrow w, t \not\models \varphi \\ w, t \not\models \varphi \text{ and } \|w - w'\|_\infty < -\rho(\varphi, w, t) &\Rightarrow w', t \not\models \varphi \end{aligned}$$

Until Rewrite

The rewrite extends from Boolean to quantitative semantics

- ▶ unbounded until

$$\varphi \mathbf{U}_{[a,+\infty)} \psi \sim \square_{[0,a]} (\varphi \mathbf{U} \psi)$$

- ▶ bounded until

$$\varphi \mathbf{U}_{[a,b]} \psi \sim \diamond_{[a,b]} \psi \wedge \varphi \mathbf{U}_{[a,+\infty)} \psi$$

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Preliminaries

- ▶ Signals: timed words $(t_i, y(t_i))_{i \leq n_y}$, with linear interpolation
- ▶ Procedure: inductive computation of robustness signals $\rho(\varphi, x, \cdot)$ on the formula structure
- ▶ Sampling: continuity, piecewise-affine property are preserved

Boolean operators

Negation

- ▶ Input signal: $(t_i, y(t_i))_{i \leq n_y}$
- ▶ Output signal: $(t_i, -y(t_i))_{i \leq n_y}$

Conjunction

- ▶ Input signals: $(t_i, y(t_i))_{i \leq n_y}, (t'_i, y'(t'_i))_{i \leq n_{y'}}$
- ▶ Output signal: $(r_i, z(r_i))_{i \leq n_z}$
Time sequence r contains t, t' , and punctual intersections $y \cap y'$
Value $z(r_i) = \min\{y(r_i), y'(r_i)\}$

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Untimed Until

Induction Property: for all $s < t$

- ▶ **Boolean Semantics** $w, s \models \varphi \mathbf{U} \psi \iff w_{\uparrow[s,t]}, s \models \varphi \mathbf{U} \psi \text{ or } (w_{\uparrow[s,t]}, s \models \square \varphi \text{ and } w, t \models \varphi \mathbf{U} \psi)$
- ▶ **Quantitative Semantics** $\rho(\varphi \mathbf{U} \psi, w, t) = \max \{ \rho(\varphi \mathbf{U} \psi, w_{\uparrow[s,t]}, s), \min \{ \rho(\square \varphi, w_{\uparrow[s,t]}, s), \rho(\varphi \mathbf{U} \psi, w, t) \} \}$

Untimed Until

Induction Property: for all $s < t$

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- ▶ Quantitative Semantics $\rho(\varphi \mathbf{U} \psi, w, t) = \max \{ \rho(\varphi \mathbf{U} \psi, w_{\uparrow[s,t]}, s), \min \{ \rho(\Box \varphi, w_{\uparrow[s,t]}, s), \rho(\varphi \mathbf{U} \psi, w, t) \} \}$

Timed Eventually

Definition: $\rho(\diamond_{[a,b]} \varphi, w, t) = \sup_{t' \in [t+a, t+b]} \rho(\varphi, w, t) = \sup_{[t+a, t+b]} y$

The maximum is reached at $t + a, t + b$, or at sample point in $\{t_i \mid t_i \in (t + a, t + b)\}$

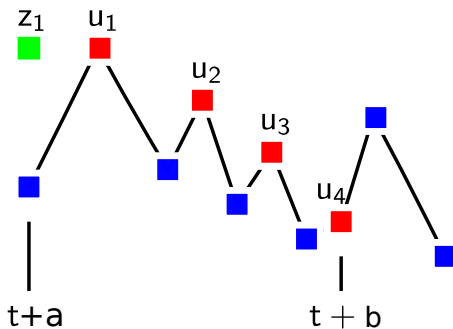
Theorem (Lemire 2006)

The maximum of a sequence of over a shifting window can be computed in linear time

Idea: we maintain an ordered set M such that

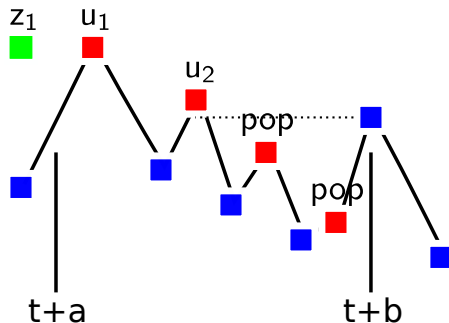
$$\max\{y(t_i) \mid i \in M\} = \max\{y(t_i) \mid t_i \in (t + a, t + b)\}$$

Timed Eventually: two steps in the algorithm



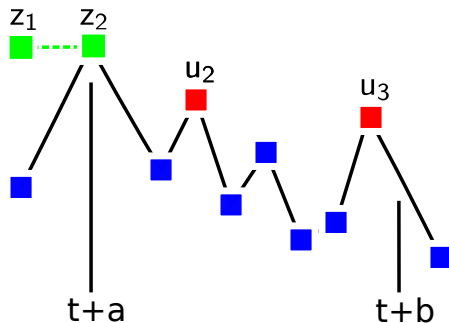
Maximum candidates $\{y(t_i) | i \in M\} = \{u_1, u_2, u_3, u_4\}$

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Timed Eventually: two steps in the algorithm



Maximum candidates $\{y(t_i) \mid i \in M\} = \{u_2, u_3\}$

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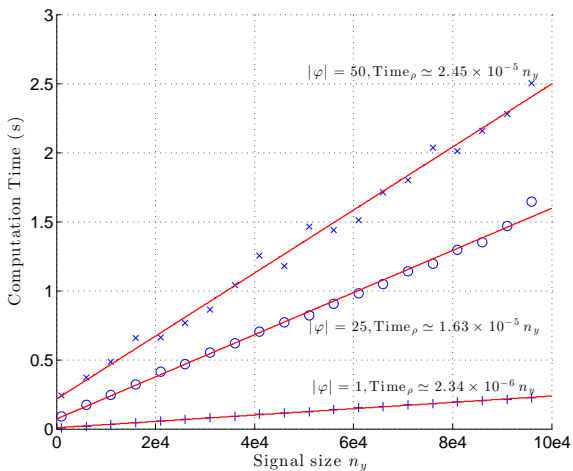
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Worst-case Complexity

- ▶ For each subformula $\psi \in \varphi$, computation time linear in the input size
- ▶ Problem: size of robustness signal can increase exponentially with formula height
- ▶ Computation time in $\mathcal{O}(|\varphi| \cdot d^{\text{h}(\varphi)} \cdot |x|)$

Experimentation: Random Signals

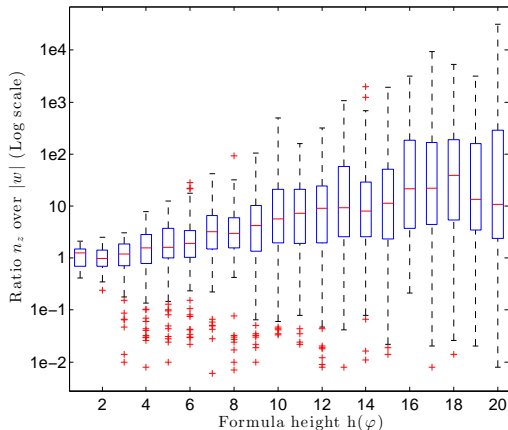
Computation is linear in size of input trace



Experimentation: Random Formulas

Exponential growth rate of robustness signal size with formula height

- ▶ average: $d \simeq 1.12$
- ▶ worst-case: $d \simeq 1.7$



Conclusion

Summary

- ▶ Enhancement to “Boolean” monitoring with reasonable computational overhead
- ▶ Piecewise affine signals: practical model for robustness computation

Perspectives

- ▶ Simulation-based approaches for verification, parameter synthesis
- ▶ Time-robustness as opposed to space-robustness