

Formal verification of secured routing protocols

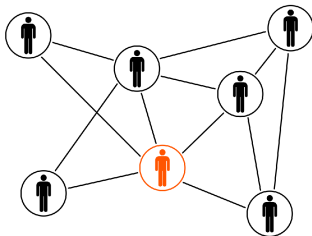
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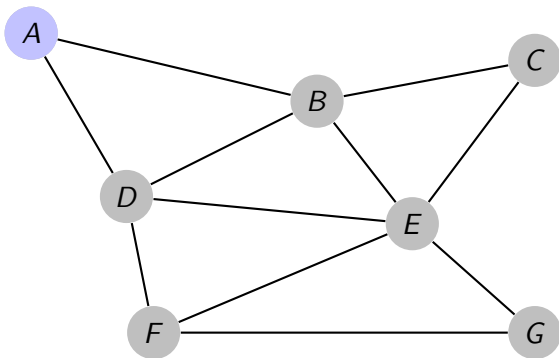


Ad Hoc Networks

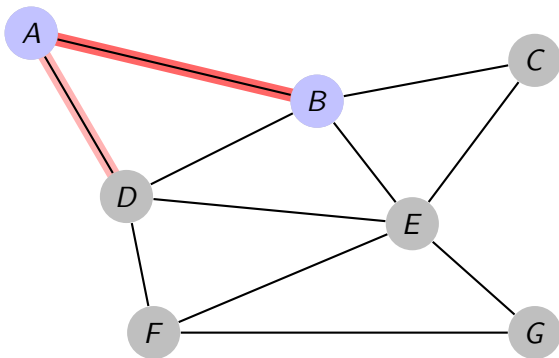


- Networks with little or no infrastructure
- Open infrastructure
- Agents can only **communicate directly with their immediate neighbors**

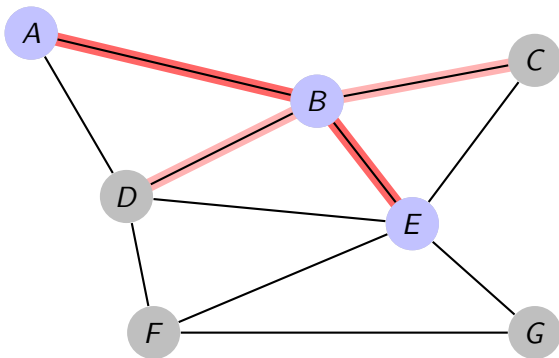
Propagation of a message in the network



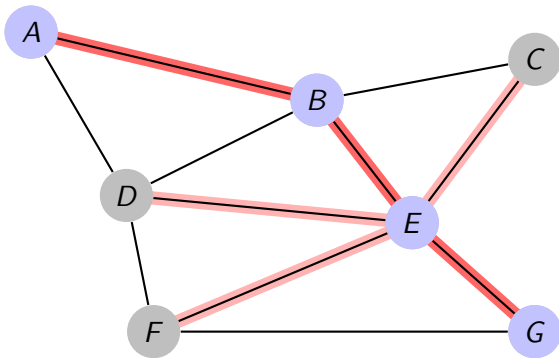
Propagation of a message in the network



Propagation of a message in the network



Propagation of a message in the network



Routing Protocols

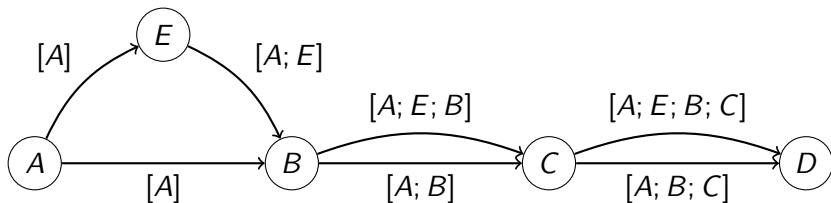
Protocol series of rules describing how each participant should behave in order to achieve a common goal

Routing goal: allowing distant nodes to communicate

Specificities of **routing** protocols:

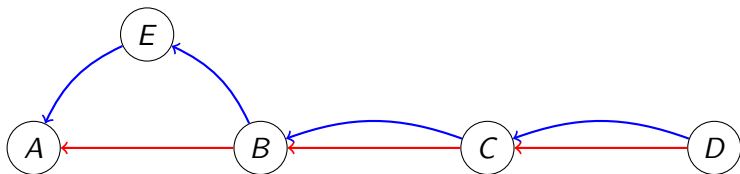
- broadcast communication
- importance of the topology of the network
- number of agents involved unknown

Example: simplified DSR



Request phase: A wants to speak to D

Example: simplified DSR



Reply phase: routes found are sent back to A

— : route [A; B; C; D]

— : route [A; E; B; C; D]

What if E was dishonest?



↔ A would get a false route to D !

⇒ Securing routing protocols

Insecure network: traditional description

Presence of an **attacker**

- may **read** every message sent on the net,
- may **intercept and send** new messages.



Results for cryptographic protocols

Attacks against protocols

Existence of an attack is **decidable** (for a bounded number of sessions).

Tools have been conceived that automatically detect logical flaws :
Proverif, AVISPA, Scyther...

but not applicable to **routing protocols** because of their
specificities

Secure Routing Protocols

Goal: allowing distant nodes to communicate by finding a path between them **while guaranteeing security**

Notable differences with other cryptographic protocols:

- broadcast communication and topology of the network
- specific tests and security properties (e.g. route correctness)
- a form of recursivity

Power of the intruder

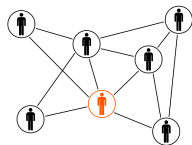
A Dolev-Yao intruder controls the network:

- hears all messages
- chooses which messages to transmit
- does not follow the protocol



Power of the intruder in an ad hoc setting:

- **broadcast** \leftrightarrow cannot delete messages
- **located** \leftrightarrow cannot hear distant messages



Our goals

Modeling and analysing secured routing protocols, taking into account :

- network topology
- less powerful intruder
- tests on the topology
- recursivity ?

Messages are abstracted by terms

Agents : a, b, \dots

Keys : k_1, k_2, \dots

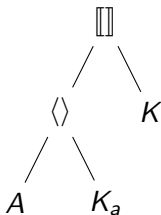
Concatenation : $\langle m_1, m_2 \rangle$

Lists: $[], a :: l$

Encryption: $\{m\}_k$

Signature : $\llbracket m \rrbracket_k$

Example: The message $\llbracket \langle A, K_a \rangle \rrbracket_K$ is represented by:



Intuition: only the structure of the message is kept.

Intruder abilities

Composition rules

$$\frac{u_1 \ u_2}{\langle u_1, u_2 \rangle}$$

$$\frac{u_1 \ u_2}{u_1 :: u_2}$$

$$\frac{u_1 \ sk(u_2)}{\llbracket u_1 \rrbracket_{sk(u_2)}}$$

$$\frac{u_1 \ u_2}{\{u_1\}_{u_2}}$$



Intruder abilities

Composition rules

$$\frac{u_1 \ u_2}{\langle u_1, u_2 \rangle} \quad \frac{u_1 \ u_2}{u_1 :: u_2} \quad \frac{u_1 \ sk(u_2)}{\llbracket u_1 \rrbracket_{sk(u_2)}} \quad \frac{u_1 \ u_2}{\{u_1\}_{u_2}}$$



Decomposition rules

$$\frac{\langle u_1, u_2 \rangle}{u_j} \quad i \in \{1, 2\} \quad \frac{u_1 :: u_2}{u_j} \quad i \in \{1, 2\} \quad \frac{\{u_1\}_{u_2} \ u_2}{u_1}$$

Optional rule:

$$\frac{\llbracket u_1 \rrbracket_{sk(u_2)}}{u_1}$$

Intruder abilities

Composition rules

$$\frac{u_1 \quad u_2}{\langle u_1, u_2 \rangle} \quad \frac{u_1 \quad u_2}{u_1 :: u_2} \quad \frac{u_1 \quad \text{sk}(u_2)}{\llbracket u_1 \rrbracket_{\text{sk}(u_2)}} \quad \frac{u_1 \quad u_2}{\{u_1\}_{u_2}}$$



Decomposition rules

$$\frac{\langle u_1, u_2 \rangle}{u_i} \quad i \in \{1, 2\} \quad \frac{u_1 :: u_2}{u_i} \quad i \in \{1, 2\} \quad \frac{\{u_1\}_{u_2} \quad u_2}{u_1}$$

Optional rule: $\frac{\llbracket u_1 \rrbracket_{\text{sk}(u_2)}}{u_1}$

Deducibility relation

A term u is **deducible** from a set of terms T , denoted by $T \vdash u$, if there exists a proof tree witnessing this fact.

Calculus

Inspired from CBS#, introduced by Nanz and Hankin

$P, Q ::=$

0

$\text{out}(u).P$

$\text{in } u[\Phi].P$

$\text{store}(u).P$

$\text{read } u \text{ then } P \text{ else } Q$

$\text{if } \Phi \text{ then } P \text{ else } Q$

$P \mid Q$

$!P$

$\text{new } m.P$

Processes

null process

emission

reception, $\Phi \in \mathcal{L}$

storage

reading

conditional, $\Phi \in \mathcal{L}$

parallel composition

replication

fresh name generation

State: $[P]_n, [S]_n, \mathcal{I}$

Formulas

$\Phi ::=$

$\text{check}(a, b)$

$\text{checkl}(c, l)$

$\text{loop}(l)$

$\text{route}(l)$

$\Phi_1 \wedge \Phi_2$

$\Phi_1 \vee \Phi_2$

$\neg\Phi$

Formula

a and b are neighbors

l is locally correct for c

existence of a loop in a list

validity of a route

conjunction

disjunction

negation

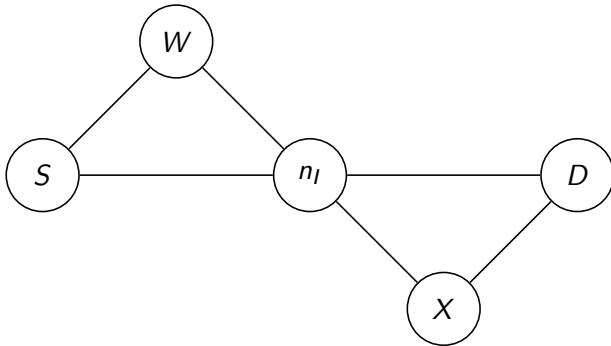
Property and tests expressed in \mathcal{L}

Expressiveness of the model

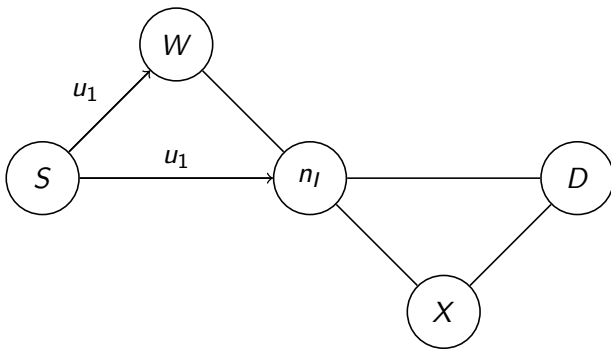
Concerning the specificities of routing protocols :

- list as a data structure
- broadcast communication and network topology
- specific tests and security properties

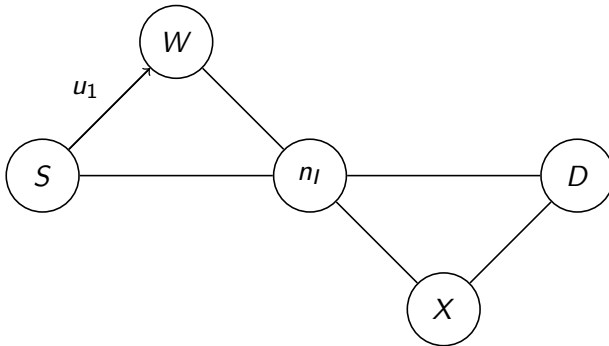
Example: source node


$$S : \text{out}(u_1).\text{in } u_2[\Phi_S]$$

Example: source node

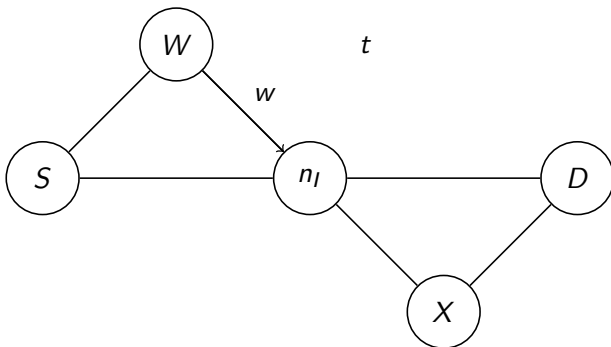

$$S : \text{out}(u_1).\text{in } u_2[\Phi_S] \rightarrow \text{in } u_2[\Phi_S]$$

Example: intermediate node



$W : \text{in } w_1[\Phi_W].\text{store}(t).\text{out}(w_2).0$

Example: intermediate node



$$\sigma = \text{mgu}(u_1, w_1) \quad \text{and} \quad w = w_2\sigma$$

Concrete transitions

Problem with concrete transitions: infinitely many possibilities

$$\begin{array}{lll} \llbracket \text{in } x.\text{out}(x) \rrbracket_n & \rightarrow & \llbracket \text{out}(t_1) \rrbracket_n \quad \text{if } \mathcal{I} \vdash t_1 \\ & \rightarrow & \llbracket \text{out}(t_2) \rrbracket_n \quad \text{if } \mathcal{I} \vdash t_2 \\ & \rightarrow & \llbracket \text{out}(t_3) \rrbracket_n \quad \text{if } \mathcal{I} \vdash t_3 \\ & & \vdots \end{array}$$

\Leftrightarrow Introduction of symbolic transitions to avoid state explosion by keeping some variables

Symbolic transition: Example

Concrete transition

$$\begin{array}{c}
 [\text{in } u[\Phi].P]_n \cup \mathcal{P}; \mathcal{S}; \mathcal{I} \\
 \rightarrow \\
 [P\sigma]_n \cup \mathcal{P}; \mathcal{S}; \mathcal{I} \\
 \text{if } \mathcal{I} \vdash t, \llbracket \Phi\sigma \rrbracket = 1 \\
 (n_l, n) \in E, \\
 \text{and } \sigma = \text{mgu}(t, u)
 \end{array}$$

Symbolic transition

$$\begin{array}{c}
 [\text{in } u[\Phi].P]_n \cup \mathcal{P}; \mathcal{S}; \mathcal{I}; \mathcal{C} \\
 \rightarrow_s \\
 [P]_n \cup \mathcal{P}; \mathcal{S}; \mathcal{I}; \\
 \mathcal{C} \cup \{\mathcal{I} \vdash u; \Phi\} \\
 \text{if } (n_l, n) \in E
 \end{array}$$

All possible concrete transitions are captured in one symbolic transition

Secrecy via constraint solving [Millen et al]

Constraint systems are used to specify secrecy preservation under a particular, finite scenario.

Scenario	Constraint System
$\text{rcv}(u_1) \xrightarrow{N_1} \text{snd}(v_1)$	$C = \left\{ \begin{array}{l} T_0 \vdash^? u_1 \\ T_0, v_1 \vdash^? u_2 \\ \dots \\ T_0, v_1, \dots, v_n \vdash^? s \end{array} \right.$
$\text{rcv}(u_2) \xrightarrow{N_2} \text{snd}(v_2)$	
\dots	
$\text{rcv}(u_n) \xrightarrow{N_n} \text{snd}(v_n)$	

where T_0 is the initial knowledge of the attacker.

Remark: Constraint Systems may be used more generally for trace-based properties, e.g. authentication.

Secrecy via constraint solving [Millen et al]

Constraint systems are used to specify secrecy preservation under a particular, finite scenario.

Scenario

$$\begin{aligned} \text{rcv}(u_1) &\xrightarrow{N_1} \text{snd}(v_1) \\ \text{rcv}(u_2) &\xrightarrow{N_2} \text{snd}(v_2) \\ &\dots \\ \text{rcv}(u_n) &\xrightarrow{N_n} \text{snd}(v_n) \end{aligned}$$

Constraint System

$$\mathcal{C} = \left\{ \begin{array}{l} T_0 \stackrel{?}{\vdash} u_1 \\ T_0, v_1 \stackrel{?}{\vdash} u_2 \\ \dots \\ T_0, v_1, \dots, v_n \stackrel{?}{\vdash} s \end{array} \right.$$

Solution of a constraint system

A substitution σ such that for every $T \vdash u \in \mathcal{C}$, $u\sigma$ is deducible from $T\sigma$, that is $T\sigma \vdash u\sigma$.

How do we show decidability ?

Step 1. Simplifying the constraint system
→ common step to all our results

Step 2. Bounding solutions
→ specific techniques for

- ① routing protocols with topology tests
- ② protocols with recursivity

Goal of the simplification: obtain simpler constraint systems

Definition (Solved constraint systems)

Solved constraint systems are of the form

$$\mathcal{C} = T_1 \overset{?}{\vdash} x_1 \wedge \cdots \wedge T_n \overset{?}{\vdash} x_n, \text{ where the } x_i \text{ are variables.}$$

We show that we can simplify constraint system and obtain solutions to solved constraint systems.

Simplification rules

$$R_{\text{ax}} : \quad \mathcal{C} \wedge T \Vdash u \rightsquigarrow \mathcal{C}$$

if $T \cup \{x \mid T' \Vdash x \in \mathcal{C}, T' \subsetneq T\} \vdash u$

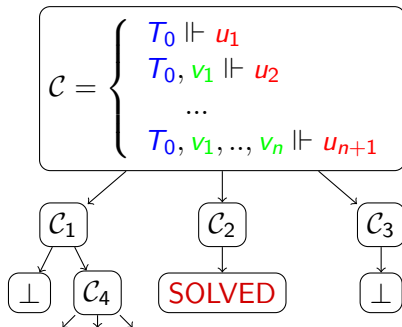
$$R_{\text{unif}} : \quad \mathcal{C} \wedge T \Vdash u \rightsquigarrow_{\sigma} \mathcal{C}\sigma \wedge T\sigma \Vdash u\sigma$$

if $\sigma = \text{mgu}(t_1, t_2)$ where $t_1, t_2 \in \text{st}(T, u)$, and $t_1 \neq t_2$

$$R_{\text{fail}} : \quad \mathcal{C} \wedge T \Vdash u \rightsquigarrow \perp$$

if $\text{vars}(T, u) = \emptyset$ and $T \not\vdash u$

$$R_{\text{f}} : \quad \mathcal{C} \wedge T \Vdash f(u, v) \rightsquigarrow \mathcal{C} \wedge T \Vdash u \wedge T \Vdash v$$



Theorem

C has a solution iff $C \rightsquigarrow_{\sigma}^* C'$ with C' in solved form.

New characterization property

if $T_i\theta \vdash u$, we have that $T_i\theta \vdash u$ using composition rules.

T_1, \dots, T_n represent a basis for deducible terms

Results for Routing protocols

We show decidability in two cases:

- decidability of an attack for a given topology
- existence of a topology leading to an attack

Fixed topology

Theorem

Let P be a protocol *without replication* and Φ a property. Deciding whether there is an attack on P and Φ for a given topology is NP-complete.

- 1 guess a path of symbolic execution
- 2 reduce to solved constraint systems (extension of the approach of Millen, Shmatikov and Comon-Lundh with an infinity of names and extended signature)
- 3 decide existence of a solution

Existence of a topology leading to an attack

Theorem

Let P be a protocol and Φ a property. Deciding *whether there exists a topology* such that there is an attack on P and Φ is NP-complete.

- Guess the edges between the nodes appearing in the protocol
- As in the case of a fixed topology, reduce the problem to solving a constraint system in solved form
- Bounding the size of the solution (in the size of the initial configuration) allows to bound the size of the graph

Protocols with recursivity tests

Aim: Analysing protocols that involve iterative or recursive operations.

- group protocols
- certification paths for public keys
- delegation rights
- secured source routing protocols

Example 1: Certificate Chains

Public keys need to be **certified**

Example (X.509 public key certificates)

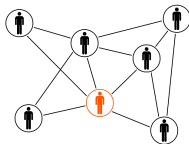
$$\begin{aligned} & \llbracket \langle A_1, \text{pub}(A_1) \rangle \rrbracket_{\text{sk}(A_2)}; \llbracket \langle A_2, \text{pub}(A_2) \rangle \rrbracket_{\text{sk}(A_3)}; \dots \\ & \dots; \llbracket \langle A_{n-1}, \text{pub}(A_{n-1}) \rangle \rrbracket_{\text{sk}(A_n)}; \llbracket \langle A_n, \text{pub}(A_n) \rangle \rrbracket_{\text{sk}(S)} \end{aligned}$$

where

- S is some trusted server, and
- each agent A_{i+1} certifies the public key $\text{pub}(A_i)$ of agent A_i .

Example 2: Secured Source Routing

To certify the route, each node signs the fact that it belongs to it.



Example (SMNDP)

The route is represented by $l_{route} = [A_n; \dots; A_1]$. The expected message is of the form

$$\begin{aligned} & \llbracket \langle A_n, A_0, l_{route} \rangle \rrbracket_{sk(A_1)}; \llbracket \langle A_n, A_0, l_{route} \rangle \rrbracket_{sk(A_2)}; \dots \\ & \dots; \llbracket \langle A_n, A_0, l_{route} \rangle \rrbracket_{sk(A_n)}. \end{aligned}$$

Remark: $\llbracket \langle A_n, A_0, l_{route} \rangle \rrbracket_{sk(A_i)}$ both depends on the list l_{route} and on its i -th element.

Our decidability results

We prove decidability for constraint systems with recursive tests:

- for link-based recursive languages \mathcal{L}_{link}

Example (Certificate chains)

$$\mathcal{L}_1 = \{ [\llbracket \langle A_1, \text{pub}(A_1) \rangle \rrbracket_{\text{sk}(A_2)}; [\llbracket \langle A_2, \text{pub}(A_2) \rangle \rrbracket_{\text{sk}(A_3)}; \dots \\ \dots; [\llbracket \langle A_n, \text{pub}(A_n) \rangle \rrbracket_{\text{sk}(S)}] \mid A_1, \dots, A_n \text{ agent names}, n \in \mathbb{N} \}$$

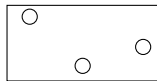
- for mapping-based languages $\mathcal{L}_{mapping}$

Example (SMNDP)

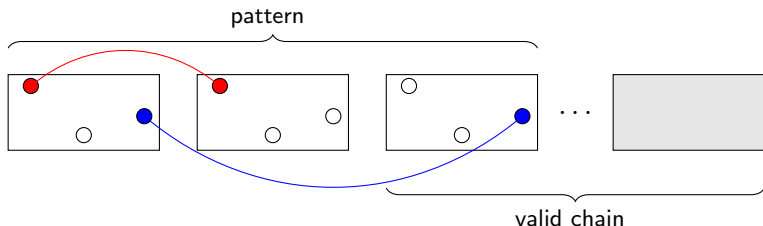
$$\mathcal{L}_2 = [[\llbracket \langle A_n, A_0, l_{route} \rangle \rrbracket_{\text{sk}(A_1)}; [\llbracket \langle A_n, A_0, l_{route} \rangle \rrbracket_{\text{sk}(A_2)}; \dots \\ \dots; [\llbracket \langle A_n, A_0, l_{route} \rangle \rrbracket_{\text{sk}(A_n)}] \mid l_{route} = [A_n, \dots, A_1], n \in \mathbb{N} \}$$

Case of link-based recursive language

Links are terms containing variables that can be instantiated by basic terms, e.g. names.



Chains in such a language are lists of links recursively constrained:



Encoding the example

Certificate lists are all built from the term $m = \llbracket \langle x, \text{pub}(y) \rangle \rrbracket_{\text{sk}(z)}$

$$\llbracket \langle x, \text{pub}(x) \rangle \rrbracket_{\text{sk}(y)} :: \llbracket \langle y, \text{pub}(y) \rangle \rrbracket_{\text{sk}(z)} :: \dots \llbracket \llbracket \langle w, \text{pub}(w) \rangle \rrbracket_{\text{sk}(s)} \rrbracket$$

The basic certificate chain is of the form $\llbracket \llbracket \langle w, \text{pub}(w) \rangle \rrbracket_{\text{sk}(s)} \rrbracket$

Theorem

Let \mathcal{L} be a link-based recursive language. Let \mathcal{C} be a constraint system and ϕ be a conjunction of \mathcal{L} -language constraints. Deciding whether \mathcal{C} and ϕ has a solution is in NP.

Intuitively, bounding the solution is done by limiting the number of possible links

Case of mapping-based languages

From a base shape b and a list of names $\ell = [a_0; \dots, a_n]$, the following terms can be built:

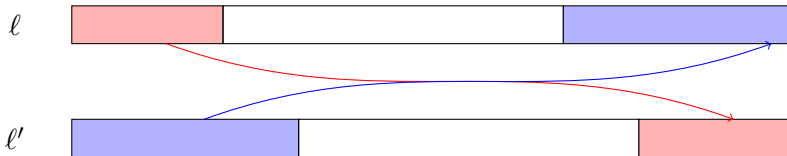
- $b_0 = b[a_0, \perp]$
- $b_1 = b[a_1, [b_0]]$
- $b_2 = b[a_2, [b_1; b_0]]$
- \vdots
- $b_n = b[a_n, [b_{n-1}; \dots; b_0]]$

$(\ell, \ell') \in \mathcal{L}$ if and only if $\ell' = [b_n; b_{n-1} \dots; b_0]$

Theorem

Let \mathcal{L} be a mapping-based recursive language. Let \mathcal{C} be a constraint system and ϕ be a conjunction of \mathcal{L} -language constraints. Deciding whether $\mathcal{C} \wedge \phi$ has a solution is in NP.

Intuition to bound the lists: the beginning of $\ell = [a_0; \dots; a_n]$ constrains the end of $\ell' = [b_n; \dots; b_0]$ and reciprocally.



Idea: cut in the **middle**

Conclusion

- Model for ad hoc networks
- Decidability for routing protocols for fixed and for unknown topologies
- NP decision procedures for security protocols with recursive tests for two classes of tests

Future work:

- Full analysis of recursive routing protocols
- Implementation
- Anonymous routing ?