The FunLoft Language

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ACI ALIDECS

Summary

- 1. FunLoft
- 2. Implementation
- 3. Multicore Programming
- 4. Future Work

FunLoft

- Inductive data types First order functions
- References Threads Events
- Schedulers + link, unlink

$$p ::= x | C(p, ..., p)$$
(patterns)

$$e ::= x | C(e, ..., e) | f(e, ..., e)$$

$$| match x with p ->e | ... | p ->e$$

$$| let x = e in e | ref e | !e | e:=e$$

$$| cooperate | thread f(e, ..., e) | join e | stop e$$

$$| unlink e | link s do e$$

$$| event | generate e with e | await e$$

$$| get_all_values e in e$$

$$| loop e | while e do e$$
(expressions)

Synchronous π **-Calculus**

• Purely functional (no references). Unique scheduler

- R. Amadio, A synchronous π-calculus, http://www.pps.jussieu.fr/~amadio
- Resources usage (memory & CPU) is polynomial in the size of the input provided some static checks (F. Dabrowski's thesis)

PACT

- FunLoft (without join)
- References can be separated (using a type and effect system):
 - threads linked to the same scheduler never interfere (cooperation!)
 - Schedulers own references only shared by threads linked to them
 - Threads own private references only accessible by them
- Consequence: absence of data-races (two threads accessing the same reference asynchronously)
- TV'06 paper was considering only a limited version (unique scheduler)
- F. Dabrowski's thesis

Implementation

- Type inference and type checking -> code production in Loft/C (pthreads + GC)
- Distinction function/module no recursive module
- Non-termination detection of recursive functions with inductive type parameters
- Instantaneous loop detection
- Stratification of references and events
- Control of thread dynamic creation
- ~ 8000 lines of code

Multicore Programming

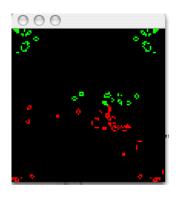
- How can a single application benefit from a multicore architecture?
- Multithreaded applications. Weak/Strong synchronisation between threads
- Benchmarks:
 - Prey/predator system with one native thread for all preys and one native thread for all predators.
 - Several rooms for migrating preys/predators: one native thread by room
 - Game Of Life (GOL) divided in several synchronised areas: one native thread by area. Strong synchronisation. Global determinism.

Synchronised Schedulers

- Asynchronous schedulers:
 - no sharing of memory (to avoid data races)
 - no event emitted from one scheduler to another scheduler (bounded size memory)
- Schedulers sharing same instants
 - no sharing of memory
 - shared events: events are common to synchronised schedulers
 - protocol for scheduler synchronisation (distributed reactive machines of SugarCubes/Junior)
- Syntax:
 - let s1 = scheduler
 - and s2 = scheduler

Multithreaded GOL

- Main differences with the one scheduler program:
 - Draw orders sent to the thread in charge of graphics
 - No global array of cells
 - Synchronised start of cells
- Difficult to get full benefit from multicore:
 - multi-threaded malloc
 - multi-threaded GC (Boehm's GC)
- Demo (10K cells, 500 instants, 1K cycles)



one scheduler real 0m26.367s user 0m24.991s sys 0m0.381s

two schedulers real 0m20.944s user 0m26.548s sys 0m0.626s

Conclusion & Future Work

- Resource control for S- π -calculus
- No data races in PACT
- Lack of formalisation: type inference, join primitive, synchronised schedulers
- Experimental implementation: Loft-C, pthreads, Boehm's GC
- Syntax for multithreaded applications running on multicore architectures
- Documentation + Available FunLoft v0.1
- Error messages!
- Specific automatic memory management?
- Language extension: exceptions? distribution (agents)?