## Schedulability and modular analysis: how to fit timing model?

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In real-time systems, program execution must fulfill timing constraints and respect deadlines. Schedulability analysis checks the feasibility of a schedule according to those timing constraints. In such analysis, a task *i* is abstracted by a *timing model*, typically (at least) made of a period  $T_i$ , a deadline  $D_i$  and a bound on the execution time  $C_i$  also named worst-case execution time (WCET).

In real-time systems (and more generally in software engineering), the trend is to reuse code: a function is designed to be used in different contexts. For instance, a function that depends on the velocity of a car may accept as parameter a range from 0 to 350 km/h. This kind of information (range) may influence the execution time and thus is taken into account by the WCET analysis. However, the constructor knows that the actual range depends on the vehicle: for instance, from 0 to 135 km/h for a smart ForTwo or from 0 to 315 km/h for a Nissan GTR. In this case, the estimated WCET may be largely overestimated if the velocity variable has a large influence on the executed path. For example, a large part of code may become dead code if the velocity never exceeds 200km (for instance, a condition "if (*vel* > 200) then XXX" where XXX is a very heavy block of instruction due to some calls to mathematical libraries).

In this context of dynamically-dead code, there is a need of modular and contextual analysis:

- analysis function by function (vs. for the whole application),
- analysis that takes into account a refined execution context (vs. one large range for each parameter).

However, as far as we know, there is no work related to this topic. Some modular analysis have been introduced, but only to refine the hardware analysis [3, 1, 2, 4]. Some infeasible path analyses exist, but only to refine the general execution path and does not take contextual information into account [7, 5, 6].

This problem could be solved by combining modular analysis, infeasible path analysis and a contextual analysis. The main difficulties of such an analysis are:

• express the context to be used in WCET analysis: what kind of context (range, one value, dynamic context)?

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- transfer the context to the analysis level: WCET analysis is derived on the binary level, but the developer knows C variables,
- analyse each function (or module) depending on the context,
- combine all modular analysis to compute the whole "context-aware" WCET,
- would the schedulability analysis and scheduling be able to integrate such bounds?

## References

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