

Comparing two UML Profiles for Non-functional Requirement Annotations: the SPT and QoS Profiles

Simona Bernardi

Università di Torino, Torino (Italy)

and

Dorina C. Petriu

Carleton University, Ottawa (Canada)

Outline

- Introduction
- Embedded automation system example
- Application of the QoS and of the SPT annotation approaches
- Comparison between the two Profiles
- Conclusion

Introduction

- **Motivation**
 - Provide an useful comparison between the two Profiles at an "appropriate moment in time"
- **Contribution**
 - Show "how to use" the new QoS Profile
 - Emphasize the main advantages/drawbacks of the two annotation approaches
 - Identification of new concepts that should be included in the two Profiles

Embedded automation system example (I)

- Distributed cyclic application activating two concurrent processes
- Process behavior:
 - Reading of a sample input from plants
 - Elaboration of the future state
 - Saving of the new state in memory and production of output for the controlled plants
- Synchronization at the end of each cycle

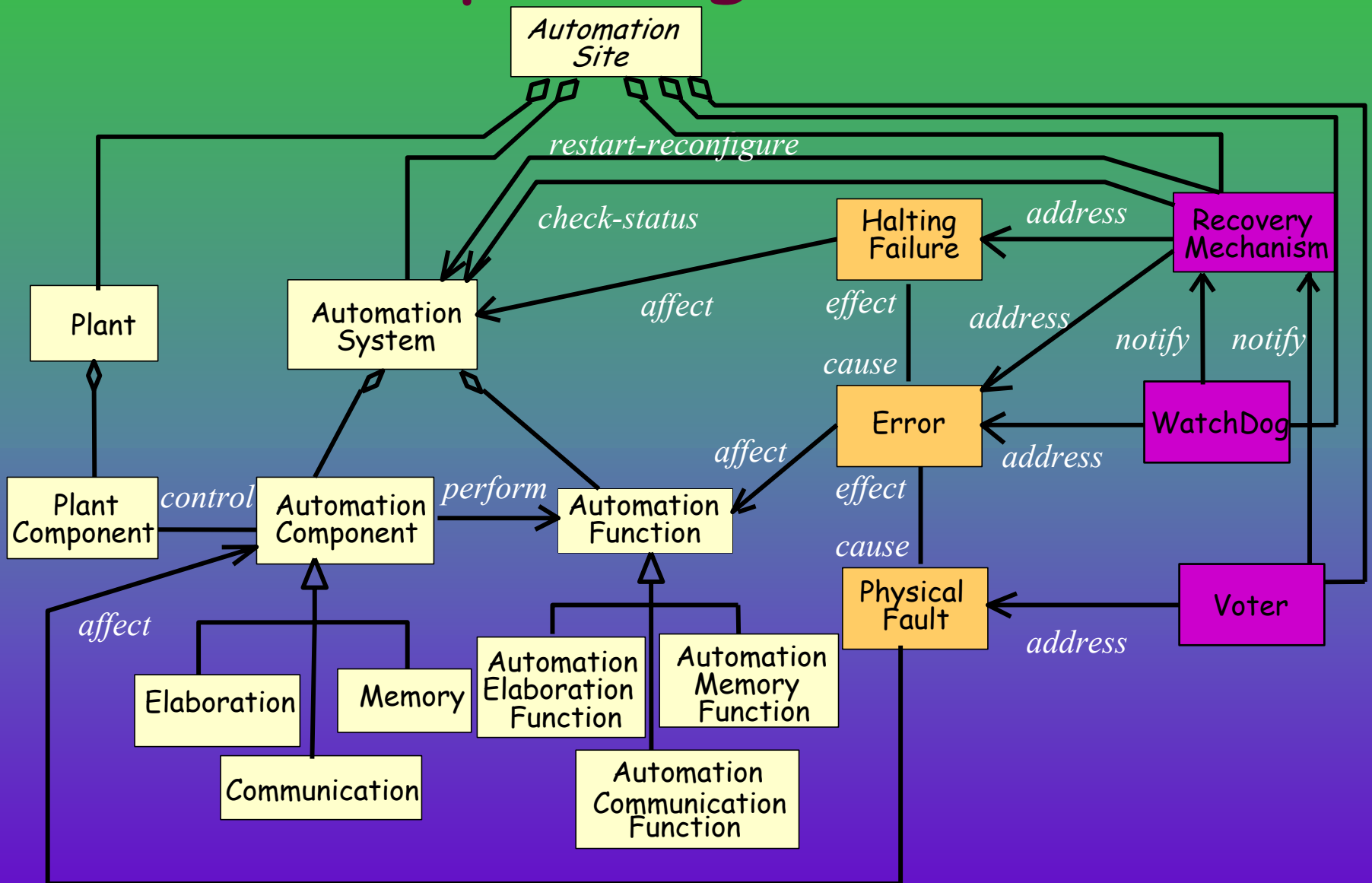
Embedded automation system example (II)

- A fault tolerance strategy is adopted including:
 - Fault masking during elaboration of the future state (hw/sw replication and voting)
 - Error detection during read/save operations (sw watchdog)
 - Error diagnosis
 - Error backward recovery or reconfiguration from failure

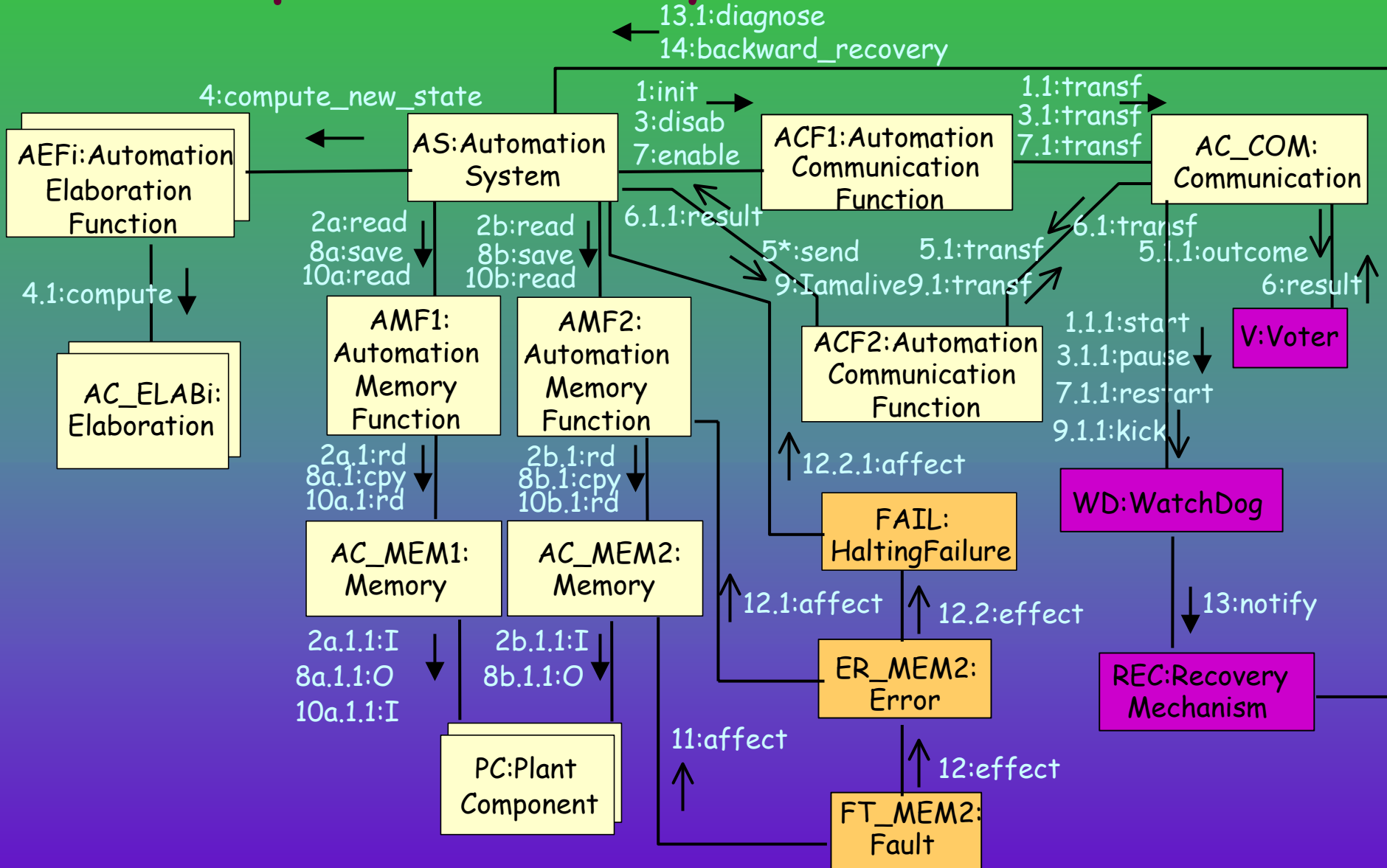
Embedded automation system example (III)

- Different non-functional reqs:
 - Timing:
 - "cycle-time to be at most of 15 ms."
 - Dependability:
 - "mean availability to be at least 98%"
 - Performability:
 - "optimal values for the timer duration of the watchdog and for the number of replicas to have the minimum *overhead* for the adopted fault tolerance strategy"

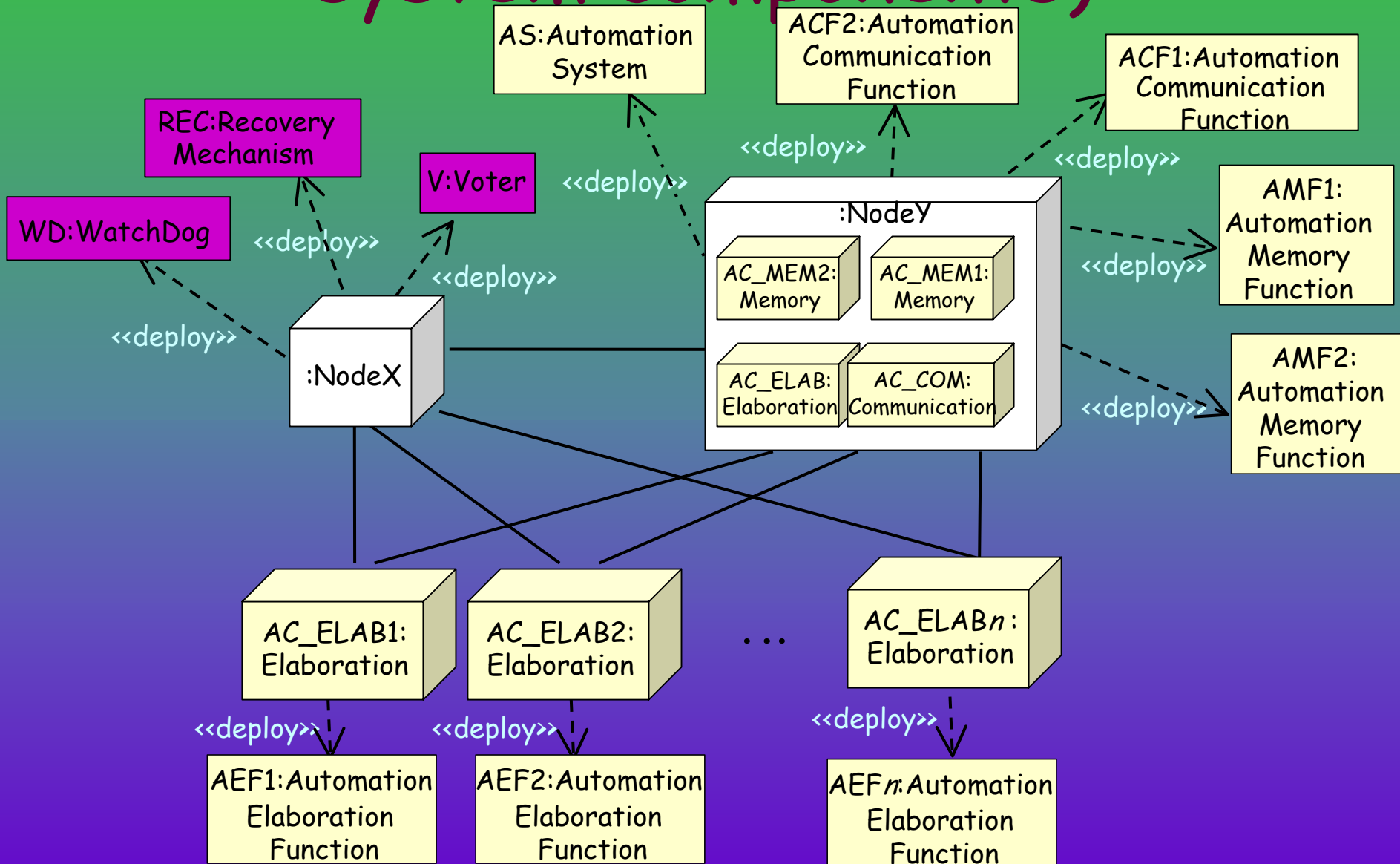
Example (logical view)



Example (Memory Fault Scenario)



Example (Physical allocation of the system components)



QoS annotation: overview

- Recently proposed with a wider scope than the SPT Profile, allowing for *user defined* QoS and Fault-Tolerance concepts
- It contains:
 - QoS subprofile - extends the General Resource Model (GRM) from the SPT profile
 - QoS model library
 - Risk Assessment subprofile
 - Fault Tolerance subprofile
- Current status
 - Adopted by OMG in June 2004 (OMG document ptc/2004-06-01)
 - Under improvements by the Finalization Task Force, preceding the formal adoption.
- No complete examples of its application

QoS annotation: approach

Three-step:

1. Define the *QoS characteristics* of interest for the analysis to be carried out in a given system domain
→ definition of template classes
2. Define the "Quality Model" for the system under study
→ the parameters of the *QoS characteristic* template classes specified in the first step are all resolved by bindings
3. Annotation of the system models through *QoS constraints*

☞ Let us apply the QoS approach to the running example for performability analysis purpose ...

QoS annotation: step 1 (I)

Efficiency category

ExpoUnit:string, UnifUnit:string

<<QoSCharacteristic>>
resource-service-time

<<QoSDimension>>
 + S: real
 {direction(decreasing),
 statisticalQualifier(distribution)}

<<QoSDimension>>
 + EXPO(mean: real)
 {unit(ExpoUnit),
 statisticalQualifier(distribution)}

<<QoSDimension>>
 + UNIF(a: real,b: real)
 {unit(UnifUnit),
 statisticalQualifier(distribution)}

For stochastic timing specification

Latency category

MinLatUnit:string,
 MaxLatUnit: string,
 JitterUnit:string

<<QoSCharacteristic>>
latency

TimerUnit: string

<<QoSCharacteristic>>
alarm-latency

<<QoSDimension>>
 + timer-duration: real
 {unit(TimerUnit)}

requestUnit:string,
 resultUnit: string,
 Unit:string

<<QoSCharacteristic>>
turn-around

<<QoSDimension>>
 + instant-of-request: real
 {unit(requestUnit)}

<<QoSDimension>>
 + instant-of-result: real
 {unit(resultUnit)}

<<QoSDimension>>
 ● + turn-around-value()
 {unit(Unit),
 direction(decreasing)}

<<description>>

context turn-around::turn-around-value

post resultOK: result =

self.instant-of-result - self.instant-of-request

QoS annotation: step 1 (II)

Dependability category

<<QoSCharacteristic>>
fault

ExpoUnit:string

<<QoSCharacteristic>>
physical-fault

<<QoSDimension>>
+ fault_rate: real
{direction(decreasing),
statisticalQualifier(distribution)}

<<QoSDimension>>
+ duration: real
{direction(decreasing),
statisticalQualifier(distribution)}

<<QoSDimension>>
+ EXPO(mean: real)
{unit(ExpoUnit),
statisticalQualifier(distribution)}

<<QoSCharacteristic>>
recoverability

<<QoSCharacteristic>>
reliability

<<QoSCharacteristic>>
fault-tolerance

<<QoSCharacteristic>>
availability

<<QoSDimension>>
+availability-value()
{direction(increasing),
statisticalQualifier(mean)}

requestUnit:string, resultUnit: string,
Unit:string

<<QoSCharacteristic>>
turn-around

FA_stat: string, IntUnit:string,
TimeUnit: string

<<QoSCharacteristic>>
overhead

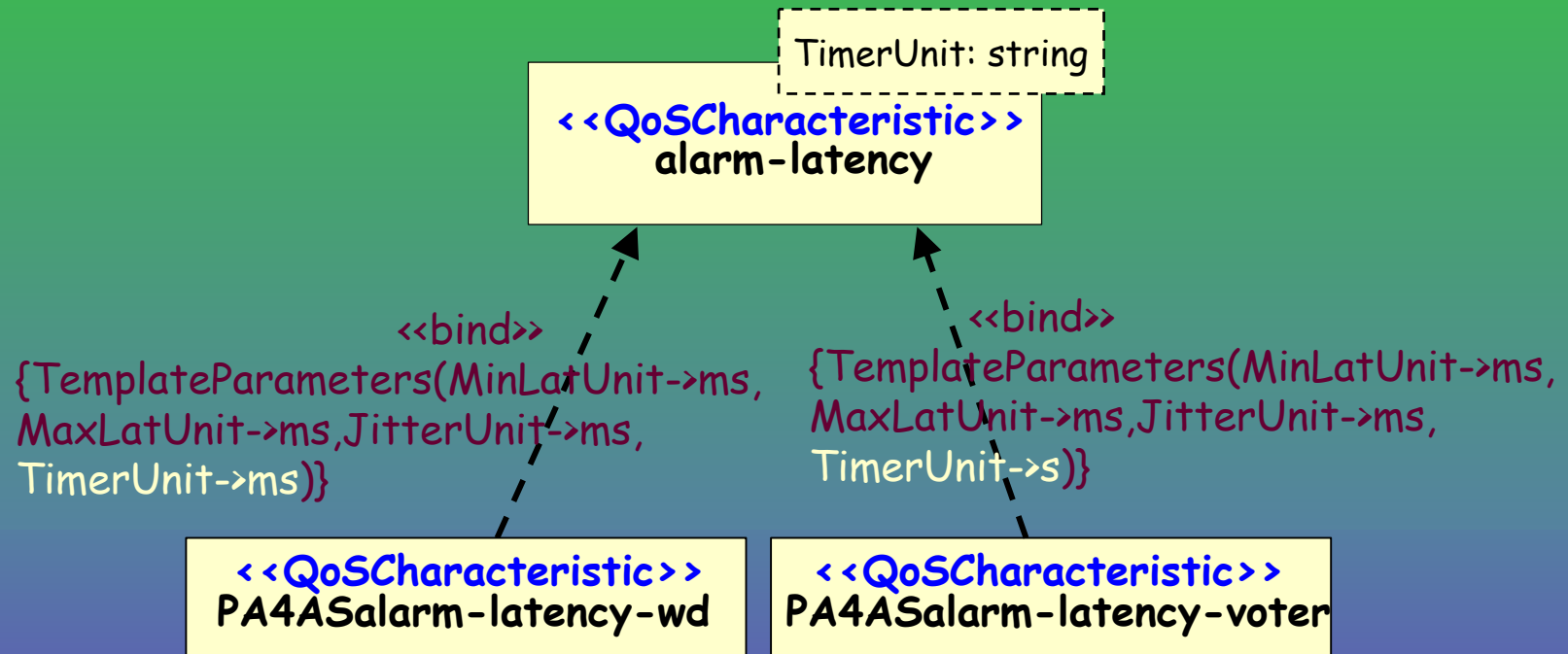
<<QoSDimension>>
+base-time: real
{unit(TimeUnit)}

<<QoSDimension>>
+false-alarm-frequency-value()
{unit(1/IntUnit)
direction(decreasing),
statisticalQualifier(FA_stat)}

<<QoSDimension>>
+time-overhead-value()
{direction(decreasing)}

<<description>>
context overhead::time-overhead-value()
post resultOK: result =
(self.OclAsType(turn-around).turn-around-value() -
self.base-time)/self.base-time

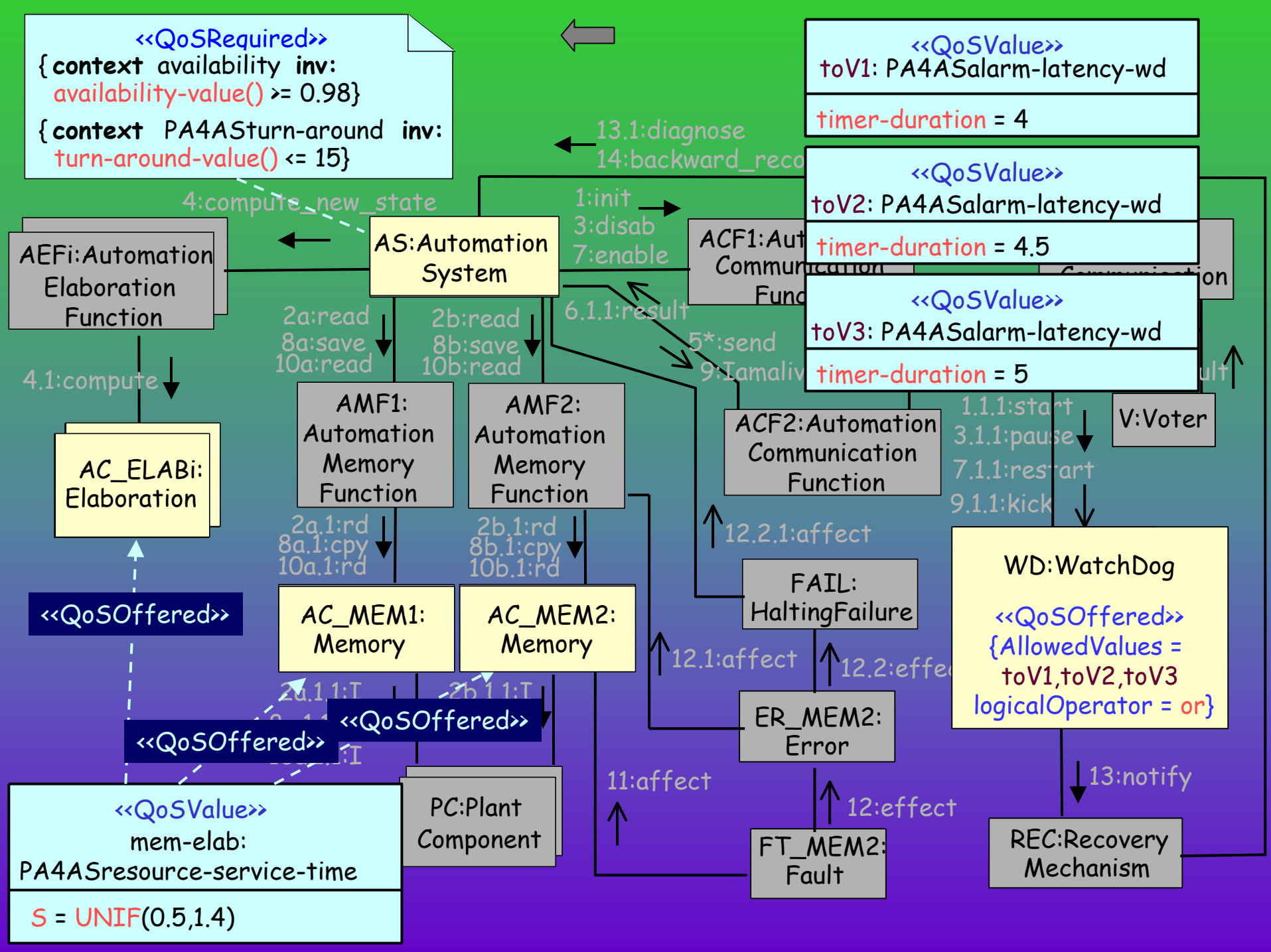
QoS annotation: step 2



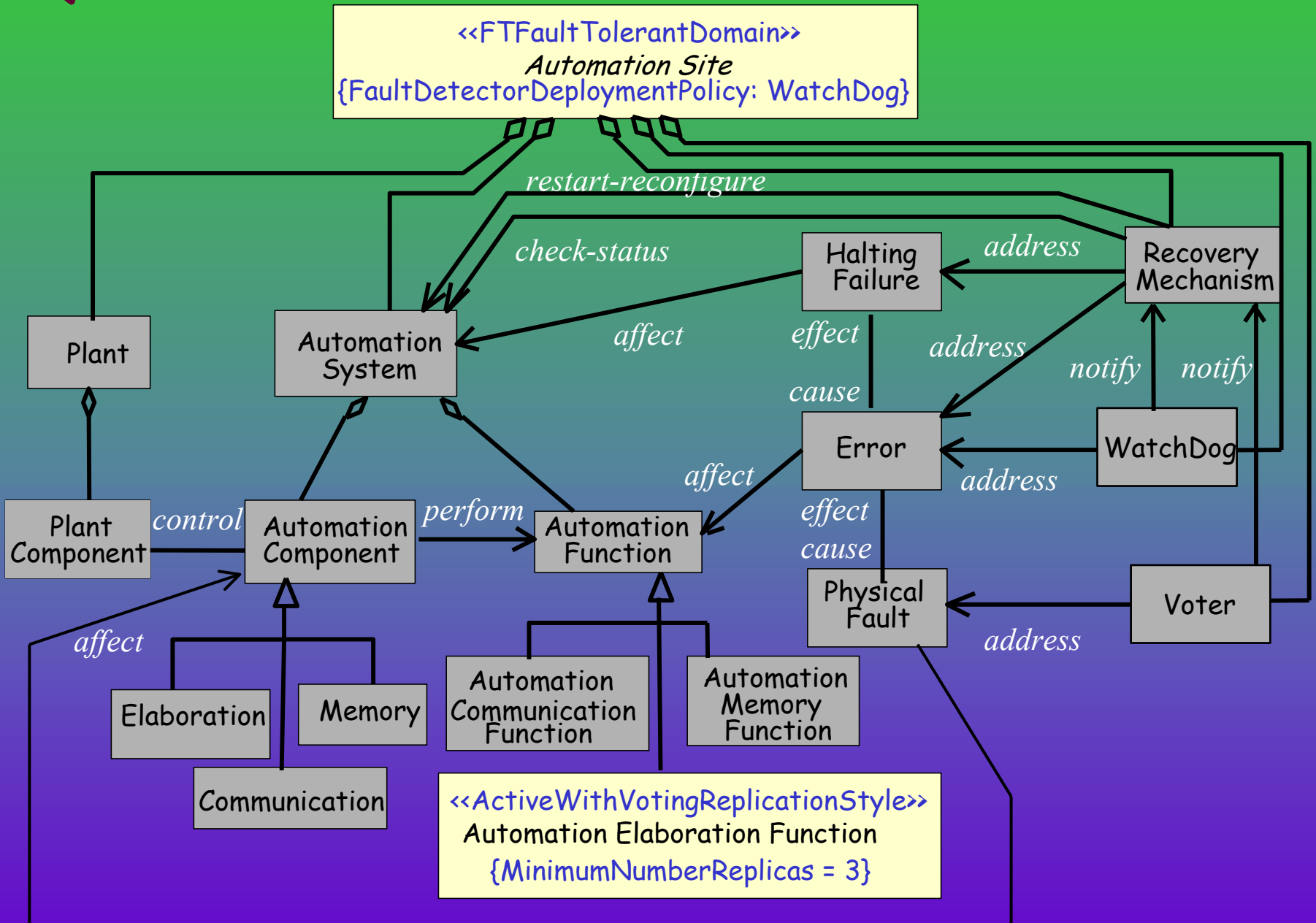
All the template class parameter must be resolved !!
→ Parametric performability models cannot be derived from UML models annotated according to the QoS Profile

QoS annotation: step 3

- Carried out by means of *QoSConstraints*:
 - *QoSRequired*, *QOSOffered*, *QoSContract*
- Three possible ways:
 1. Attach a note with a *QoSConstraint* written in OCL to a model elements (e.g.)
 2. Connect the constrained element with an instance of a class stereotyped as *QoSValue* by a *QoSConstraint* dependency (e.g.)
 3. Stereotype the constrained model element with a *QoSConstraint* and use *AllowedValue* and *LogicalOperator* properties to reference a set of *QoSValues* and their relationships (e.g.)



QoS annotation: FT architectures



SPT annotation: overview

- **First attempt** to extend UML with basic timing and concurrency concepts for expressing non-functional reqs/properties
- It contains:
 - General Resource Modeling Framework (GRM)
 - Analysis Models (**schedulability** and **performance** sub-profiles)
 - Infrastructure Models (Real-Time CORBA)
- **Current status:**
 - Formal OMG adoption in Sept. 2003
 - On-going process of issuing a new RFP for V2 to bring it in line with UML2.0
 - Applied on several case studies/examples
 - Integrated in several UML commercial tools (e.g., Artisan Real-time Studio, Rhapsody)

SPT annotation: approach

- More straightforward to apply than QoS but less flexible
- Provides a set of stereotypes and related attributes that can be used **directly** for the annotation of the system models
- **No customization possibilities**

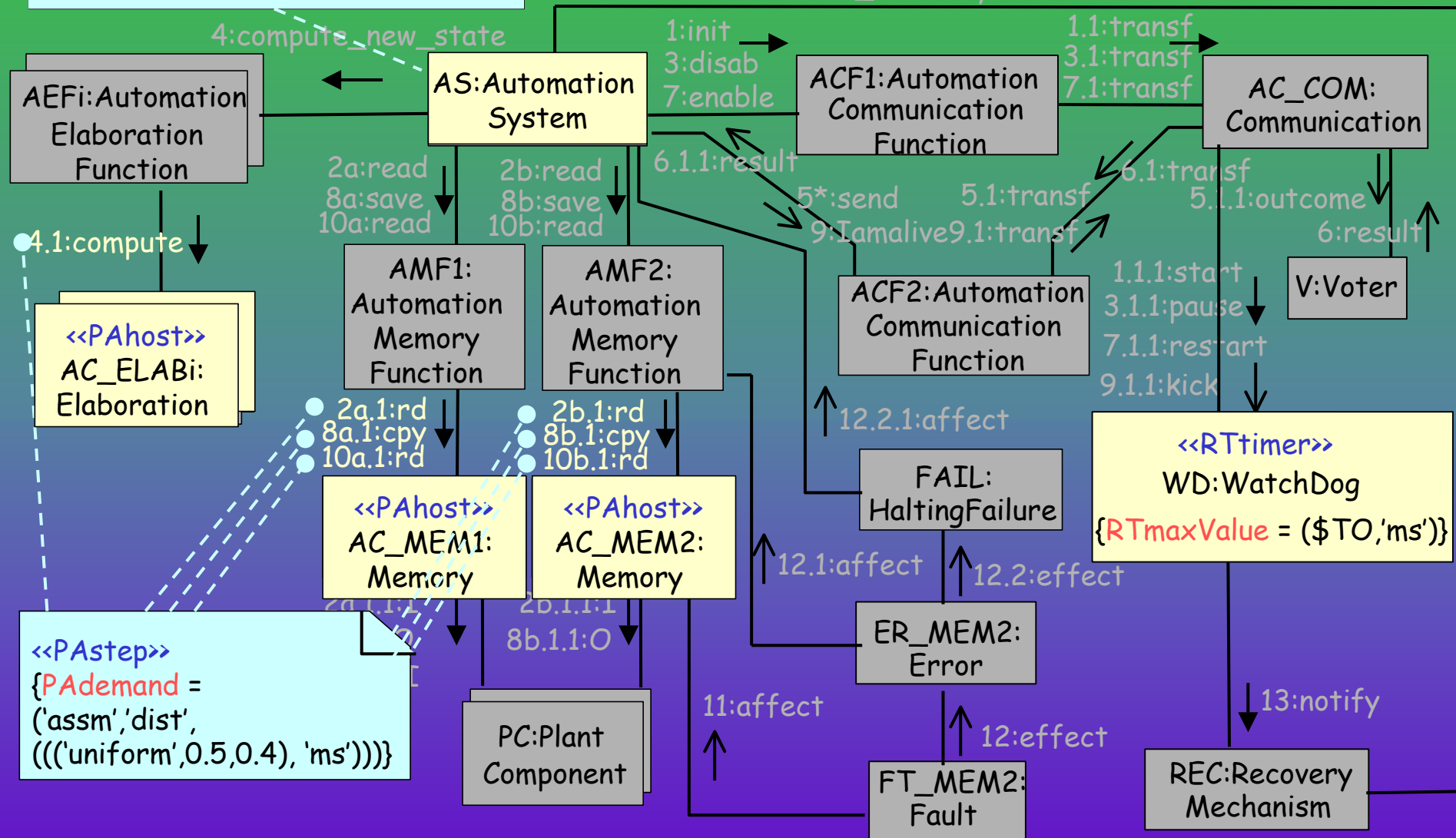
☞ Let us apply the SPT approach to the running example for performability analysis purpose ...

SPT annotation

<<description>>

dependability and timing reqs
to be satisfied:

{**availability** = ('req','min',(0.98)),
cycle-time = ('req','max',(15,'ms'))}



QoS vs/ SPT Profile (I)

- ✓ Type of analysis supported
 - STP limited to schedulability and performance
- ✓ Specification level
 - Both "class" and "instance" levels in principle, "instance" level in practise
- ✓ Annotation approach
 - three-step based for QoS, more straightforward for SPT
- ✓ Annotation in the system models
 - Which UML models can be annotated ?
 - How many different ways ?

QoS vs/ SPT Profile (II)

- ✓ Parameterization capabilities
 - In SPT, by convention parameters are expressed by symbolic variables prefixed by "\$"
- ✓ Discrimination of the type of specification
 - QoS: *QoSRequired*, *QOSOffered*, *QOSContract*
 - SPT: modifying field for assumptions, requirements, metrics, properties ('assm', 'req', 'msr', 'pred')
- ✓ Specification of stochastic timings and related issues
 - SPT: general format for time value expressions including PdFs - "open list" of PdFs
 - QoS: no support for PdF specification
- ✓ Basic common concepts: resources

Conclusion

- ✓ **Summary of the work**
 - Application of SPT and QoS Profiles to embedded automation system domain for performability analysis purpose
 - Comparison between the two annotation approaches
- ✓ **From the comparative analysis comes up...**
 - New concepts are needed in both the Profiles to express time interval between two arbitrary events
 - A common agreement on the specification of complex timing values (especially on stochastic timing) should to be reached
 - In the QoS approach the parameterization of models is still an open problem

END



Stochastic timings and related issues

