

The Laplace Transform

Why?

The Laplace Transform

Why?

Important tool to solve and reason about stationary and linear differential equations

The Laplace Transform

Why?

Important tool to solve and reason about stationary and linear differential equations

and to understand design tools such as Simulink, Lustre-Scade

The Laplace Transform

Why?

Important tool to solve and reason about stationary and linear differential equations

and to understand design tools such as Simulink, Lustre-Scade

- Definition
- Differential equations
- Exponential Functions
- Examples
- Initial Value and Final Value Theorems

Definition

$$\mathcal{L}x(s) = \int_0^{\infty} x(t)e^{-st}$$

(under the existence condition)

Definition

$$\mathcal{L}x(s) = \int_0^{\infty} x(t)e^{-st}$$

(under the existence condition)

Why???

Differential equations

Because the Laplace transform enables transforming ordinary differential equations into algebraic equations (that we know how to manipulate usually)

thanks to two properties:

Differential equations

Because the Laplace transform enables transforming ordinary differential equations into algebraic equations (that we know how to manipulate usually)

thanks to two properties:

1. **Linearity:**

$$\mathcal{L}(\alpha x + \beta y) = \alpha \mathcal{L}x + \beta \mathcal{L}y$$

Differential equations

Because the Laplace transform enables transforming ordinary differential equations into algebraic equations (that we know how to manipulate usually)

thanks to two properties:

1. **Linearity:**

$$\mathcal{L}(\alpha x + \beta y) = \alpha \mathcal{L}x + \beta \mathcal{L}y$$

2. The derivatives are transformed into **products:**

$$\mathcal{L}(x')(s) = s\mathcal{L}x(s) - x(0)$$

Proof

Integration by parts

$$\int_0^{\infty} x'(t)e^{-st} = [x(t)e^{-st}]_0^{\infty} - \int_0^{\infty} x(t)(-s)e^{-st}$$

if $\lim_{t \rightarrow \infty} x(t)e^{-st} = 0$, we have

$$\mathcal{L}(x')(s) = s\mathcal{L}x(s) - x(0)$$

Example: an ODE

First-order linear differential equation with constant coefficients:

$$y' = -ay + bx$$

Example: an ODE

First-order linear differential equation with constant coefficients:

$$y' = -ay + bx$$

$$\mathcal{L}(y')(s) = s\mathcal{L}y(s) - y(0) = -a\mathcal{L}y(s) + b\mathcal{L}x(s)$$

Example: an ODE

First-order linear differential equation with constant coefficients:

$$y' = -ay + bx$$

$$\mathcal{L}(y')(s) = s\mathcal{L}y(s) - y(0) = -a\mathcal{L}y(s) + b\mathcal{L}x(s)$$

$$(s + a)\mathcal{L}y(s) = b\mathcal{L}x(s) + y(0)$$

Example: an ODE (cont'd)

$$(s + a)\mathcal{L}y(s) = b\mathcal{L}x(s) + y(0)$$

$$\mathcal{L}y(s) = \frac{1}{s + a}(b\mathcal{L}x(s) + y(0))$$

Example: an ODE (cont'd)

$$(s + a)\mathcal{L}y(s) = b\mathcal{L}x(s) + y(0)$$

$$\mathcal{L}y(s) = \frac{1}{s + a}(b\mathcal{L}x(s) + y(0))$$

This differential equation has been “solved” and the solution is a **rational fraction**

Exponential Functions

The **exponential (gamma) functions** are transformed into **rational fractions**:

$$\gamma_n(t) = \frac{t^n}{n!} e^{-\lambda t}$$

Exponential Functions

The **exponential (gamma) functions** are transformed into **rational fractions**:

$$\gamma_n(t) = \frac{t^n}{n!} e^{-\lambda t}$$

$$\mathcal{L}\gamma_n(s) = \left(\frac{1}{s + \lambda} \right)^{n+1}$$

Proof

By induction :

Proof

By induction : $n = 0$

Proof

By induction : $n = 0$

$$\int_0^{\infty} e^{-\lambda t} e^{-st} = \int_0^{\infty} e^{-(s+\lambda)t} = \left[-\frac{e^{-(s+\lambda)t}}{s+\lambda} \right]_0^{\infty} = \frac{1}{s+\lambda}$$

provided that $\lim_{t \rightarrow \infty} e^{-(s+\lambda)t} = 0$

Proof

By induction : $n = 0$

$$\int_0^{\infty} e^{-\lambda t} e^{-st} = \int_0^{\infty} e^{-(s+\lambda)t} = \left[-\frac{e^{-(s+\lambda)t}}{s+\lambda} \right]_0^{\infty} = \frac{1}{s+\lambda}$$

provided that $\lim_{t \rightarrow \infty} e^{-(s+\lambda)t} = 0$

$n + 1$

Integration by parts

Proof

By induction : $n = 0$

$$\int_0^{\infty} e^{-\lambda t} e^{-st} = \int_0^{\infty} e^{-(s+\lambda)t} = \left[-\frac{e^{-(s+\lambda)t}}{s+\lambda} \right]_0^{\infty} = \frac{1}{s+\lambda}$$

provided that $\lim_{t \rightarrow \infty} e^{-(s+\lambda)t} = 0$

$n + 1$

Integration by parts

$$\begin{aligned} \int_0^{\infty} \frac{t^{n+1}}{(n+1)!} e^{-\lambda t} e^{-st} &= \left[-\frac{t^{n+1}}{(n+1)!} \frac{e^{-(s+\lambda)t}}{s+\lambda} \right]_0^{\infty} \\ &\quad - \int_0^{\infty} -\frac{t^n}{n!} \frac{e^{-(s+\lambda)t}}{s+\lambda} \\ &= \frac{1}{s+\lambda} \int_0^{\infty} \frac{t^n}{n!} e^{-(s+\lambda)t} \end{aligned}$$

Examples of signal

Step signal: $u(t) = \begin{cases} 1 & \text{si } t \geq 0 \\ 0 & \text{otherwise} \end{cases}$

Examples of signal

Step signal: $u(t) = \begin{cases} 1 & \text{si } t \geq 0 \\ 0 & \text{otherwise} \end{cases}$

This is the case where $n = 0, \lambda = 0$

Examples of signal

Step signal: $u(t) = \begin{cases} 1 & \text{si } t \geq 0 \\ 0 & \text{otherwise} \end{cases}$

This is the case where $n = 0, \lambda = 0$

$$\mathcal{L}u(s) = \frac{1}{s}$$

Examples of signal

Step signal: $u(t) = \begin{cases} 1 & \text{si } t \geq 0 \\ 0 & \text{otherwise} \end{cases}$

This is the case where $n = 0, \lambda = 0$

$$\mathcal{L}u(s) = \frac{1}{s}$$

Ramp signal: $r(t) = u(t)t$

Examples of signal

Step signal: $u(t) = \begin{cases} 1 & \text{si } t \geq 0 \\ 0 & \text{otherwise} \end{cases}$

This is the case where $n = 0, \lambda = 0$

$$\mathcal{L}u(s) = \frac{1}{s}$$

Ramp signal: $r(t) = u(t)t$ This is the case where
 $n = 1, \lambda = 0$

Examples of signal

Step signal: $u(t) = \begin{cases} 1 & \text{si } t \geq 0 \\ 0 & \text{otherwise} \end{cases}$

This is the case where $n = 0, \lambda = 0$

$$\mathcal{L}u(s) = \frac{1}{s}$$

Ramp signal: $r(t) = u(t)t$ This is the case where $n = 1, \lambda = 0$

$$\mathcal{L}r(s) = \frac{1}{s^2}$$

Other signals

Sinusoid: $\sin(\omega t)$

Other signals

Sinusoid: $\sin(\omega t)$

$$\sin(\omega t) = \frac{e^{i\omega t} - e^{-i\omega t}}{2i}$$

Other signals

Sinusoid: $\sin(\omega t)$

$$\sin(\omega t) = \frac{e^{i\omega t} - e^{-i\omega t}}{2i}$$

$$\begin{aligned}\mathcal{L}\sin(s) &= \frac{1}{2i} \left(\frac{1}{s - i\omega} - \frac{1}{s + i\omega} \right) \\ &= \frac{1}{2i} \frac{s + i\omega - (s - i\omega)}{(s - i\omega)(s + i\omega)} \\ &= \frac{\omega}{s + \omega}\end{aligned}$$

Example of System

First-order system:

$$\mathcal{L}y(s) = \frac{1}{s + a}(b\mathcal{L}x(s) + y(0))$$

Response to a step signal that starts with $y(0) = 0$:

Example of System

First-order system:

$$\mathcal{L}y(s) = \frac{1}{s+a}(b\mathcal{L}x(s) + y(0))$$

Response to a step signal that starts with $y(0) = 0$:

$$\mathcal{L}x(s) = \frac{1}{s}$$

$$\mathcal{L}y(s) = \frac{b}{s(s+a)}$$

Resolution

Partial fraction decomposition: $\frac{b}{s(s+a)} = \frac{A}{s} + \frac{B}{s+a}$

Resolution

Partial fraction decomposition: $\frac{b}{s(s+a)} = \frac{A}{s} + \frac{B}{s+a}$

$$\frac{bs}{s(s+a)} = \frac{As}{s} + \frac{Bs}{s+a}$$

$$\frac{b}{s+a} = A + \frac{Bs}{s+a}$$

$$s = 0$$

$$\frac{b}{0+a} = A$$

$$\frac{b(s+a)}{s(s+a)} = \frac{A(s+a)}{s} + \frac{B(s+a)}{s+a}$$

$$\frac{b}{s} = \frac{A(s+a)}{s} + B$$

$$s = -a$$

$$\frac{b}{-a} = B$$

Resolution

Partial fraction decomposition: $\frac{b}{s(s+a)} = \frac{A}{s} + \frac{B}{s+a}$

$$\frac{bs}{s(s+a)} = \frac{As}{s} + \frac{Bs}{s+a}$$

$$\frac{b}{s+a} = A + \frac{Bs}{s+a}$$

$$s = 0$$

$$\frac{b}{0+a} = A$$

$$\frac{b(s+a)}{s(s+a)} = \frac{A(s+a)}{s} + \frac{B(s+a)}{s+a}$$

$$\frac{b}{s} = \frac{A(s+a)}{s} + B$$

$$s = -a$$

$$\frac{b}{-a} = B$$

$\mathcal{L}y(s) = \frac{b}{a} \left(\frac{1}{s} - \frac{1}{s+a} \right)$. Hence, $y(t) = \frac{b}{a} (1 - e^{-at})$

Other Method

Using the Laplace approach, we need find the **poles** (roots of the polynomials)

However, we know how to do this for polynomials of degrees less than or equal to 5 (already difficult beyond degree 2)

Otherwise, **numerical integration**

Other Properties

Initial Value Theorem:

$$\lim_{t \rightarrow 0} x(t) = \lim_{s \rightarrow \infty} s \mathcal{L}x(s)$$

if the limits exist

Final Value Theorem:

$$\lim_{t \rightarrow \infty} x(t) = \lim_{s \rightarrow 0} s \mathcal{L}x(s)$$

if the limits exist

Proof

Initial Value Theorem:

$$\mathcal{L}x'(s) + x(0) = s\mathcal{L}x(s)$$

Proof

Initial Value Theorem:

$$\mathcal{L}x'(s) + x(0) = s\mathcal{L}x(s)$$

$$\lim_{s \rightarrow \infty} \mathcal{L}x'(s) = 0$$

Proof

Initial Value Theorem:

$$\mathcal{L}x'(s) + x(0) = s\mathcal{L}x(s)$$

$$\lim_{s \rightarrow \infty} \mathcal{L}x'(s) = 0$$

Initial Value Theorem:

$$\mathcal{L}x'(s) + x(0) = s\mathcal{L}x(s)$$

Proof

Initial Value Theorem:

$$\mathcal{L}x'(s) + x(0) = s\mathcal{L}x(s)$$

$$\lim_{s \rightarrow \infty} \mathcal{L}x'(s) = 0$$

Initial Value Theorem:

$$\mathcal{L}x'(s) + x(0) = s\mathcal{L}x(s)$$

$$\lim_{s \rightarrow 0} \mathcal{L}x'(s) = \int_0^{\infty} x'(t) dt = [x(t)]_0^{\infty} = \lim_{t \rightarrow \infty} x(t) - x(0)$$

Applications

How to know the **final value** of the responses of a system to a step signal **without calculating the solution**?

Take the Laplace transform of the response (in the running example):

$$\mathcal{L}y(s) = \frac{b}{s(s+a)}$$

Applications

How to know the **final value** of the responses of a system to a step signal **without calculating the solution**?

Take the Laplace transform of the response (in the running example):

$$\mathcal{L}y(s) = \frac{b}{s(s+a)}$$

It suffices to use the **Final Value Theorem**:

$$\lim_{s \rightarrow 0} s \frac{b}{s(s+a)} = \lim_{s \rightarrow 0} \frac{b}{(s+a)} = \frac{b}{a}$$