

# Translation of DOL Application Specification to BIP

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VERIMAG

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- Joint work with Iuliana Bacivarov, Wolfgang Haid, Kai Huang and Lothar Thiele from ETHZ-TIK
- DOL is a specification framework for dataflow embedded systems:
  - Specifications for the Application, Hardware and Mapping
  - Behavior of the Application is C/C++ code
- Translation of DOL Application Specification without taking into account the hardware
  - Automatic translation of DOL C/C++ behavior code to BIP behavior model
    - Translation based on a model of C/C++ code
  - A model of the software independently of the platform

## Introduction

### Translating a DOL Application to a BIP Model

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# DOL is a Specification Framework for Data Flow Embedded Systems

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- A specification for the application
  - 3 basic entities: process, software channel and connection
  - All processes have the same organisation: an `init` procedure then a continuous loop of the `fire` procedure
  - The behavior of procedures `init` and `fire` is described by C language with some added constraints:
    - There is some special functions: `DOL_write` and `DOL_read` for the data transfers

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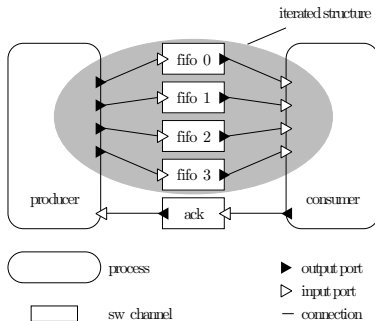
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# Example of DOL process



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## Process Model

- |  |                |
|--|----------------|
| 1: <b>procedure</b> INIT(DOLProcess <i>p</i> ) | initialization |
| 2:     initialize local data structures        |                |
| 3: <b>end procedure</b>                        |                |
| 4: <b>procedure</b> FIRE(DOLProcess <i>p</i> ) | execution      |
| 5:     DOL_read(INPUT, size, buf)              | blocking read  |
| 6:     manipulate                              |                |
| 7:     DOL_write(OUTPUT, size, buf)            | blocking write |
| 8: <b>end procedure</b>                        |                |
- 

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- A specification of hardware architecture
  - Includes all processors, memories, buses and possible connections between buses and memories
  - Each hardware element has a type corresponding to a real hardware element
  - Hardware elements can be parameterized
- A specification of the mapping of an application on the hardware architecture
  - Includes the mapping of processes to processors and of software channels to hardware channels
  - Includes schedules for processors and buses

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# Example of DOL Hardware Architecture

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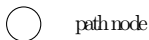
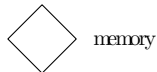
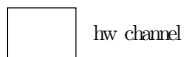
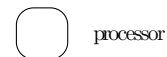
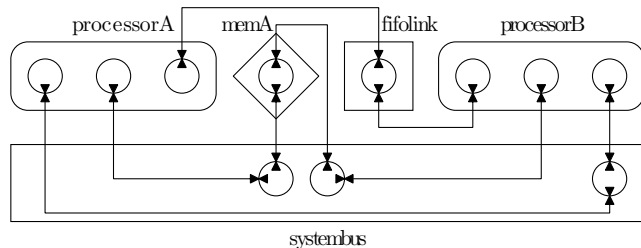
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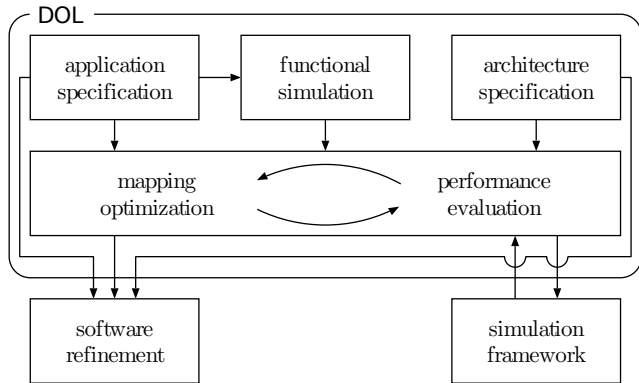
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# DOL can Optimize the Load of Hardware Architecture

- From the results of:
  - A purely functional simulation: **does not take into account** the hardware architecture
  - An instruction accurate simulation: **takes into account** the hardware architecture
- From the performance analysis, an optimization of the mapping is done with genetic algorithms

**Application** ::= (**Process**)<sup>+</sup> (**SWChannel**)<sup>+</sup> (**Connection**)<sup>+</sup>

**Process** ::= (*ProcInPort* + *ProcOutPort*)<sup>+</sup> **Behavior**

**SWChannel** ::= *Size RecvPort SendPort*

**Connection** ::= (*ProcOutPort RecvPort*) + (*SendPort ProcInPort*)

**Behavior** ::= **procedure** **procedure**

**procedure** ::= (*variable\_declaration*)\* **statement\_group**

**statement\_group** ::= (**for** + **if** + **switch** + *DOL\_read* +  
*DOL\_write* + *simple\_statement* +  
**statement\_group**)<sup>+</sup>

**if** ::= *condition* **statement\_group**  
[ **statement\_group** ]

**for\_statement\_group** ::= (*simple\_statement* +  
**statement\_group**) \*

**for** ::= **for\_statement\_group** *condition*  
**for\_statement\_group**  
**statement\_group**

**switch** ::= *variable* (**case**)<sup>+</sup> [**default**]  
**case** ::= *value* **statement\_group**  
**default** ::= *default* **statement\_group**

# Restriction of C/C++ Code Accepted in DOL Behavior

- All variable declarations should be at the beginning of `init` and `fire` procedures
- Only one `return` by procedure
- No `goto`
- All `DOL_read`, `DOL_write`, `DOL_detach` in the `init` and `fire` procedure: not in external functions called in those procedure

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# Example of Translation of DOL software channel

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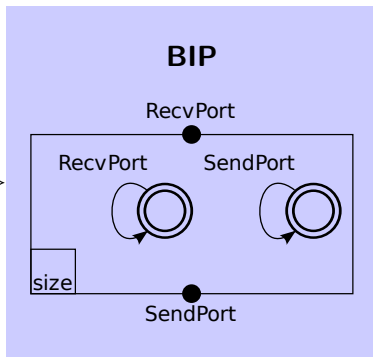
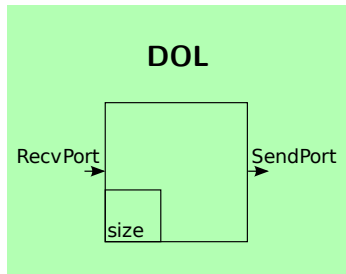
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**SWChannel** ::= *Size RecvPort SendPort*

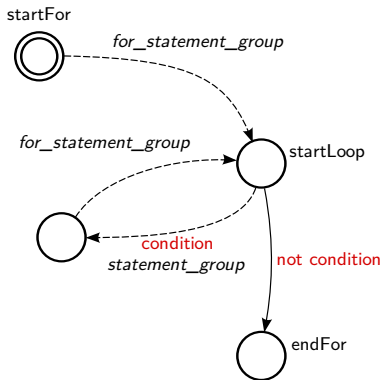


**Connection**<sub>DOL</sub> ::= *output input*

**Connection**<sub>BIP</sub> ::= *connector(output, input)*

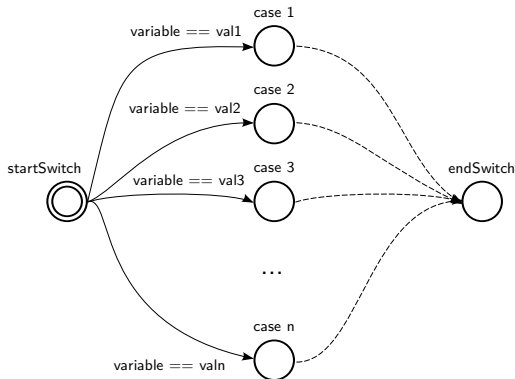
- For each connection corresponds one BIP connector
  - It will transfer the size and the address of the data to be transferred;
  - It will also synchronise the two components during the copy of the data.

**for ::= for\_statement\_group condition**  
**statement\_group for\_statement\_group**

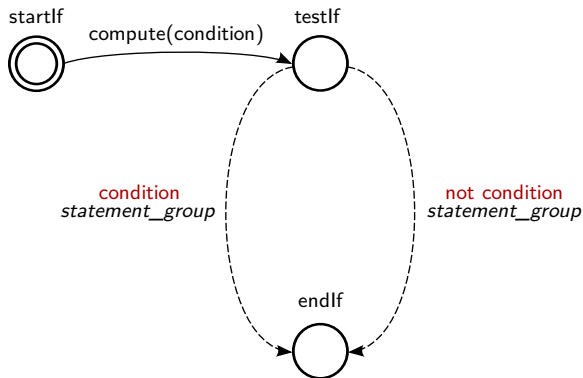
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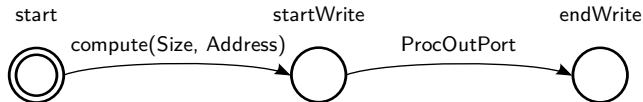
**switch** ::= *variable*.(**case**)<sup>+</sup>. [**default**]  
**case** ::= *value*.**statement\_group**  
**default** ::= *default*.**statement\_group**



**if** ::= *condition* **statement\_group** [ **statement\_group** ]



**DOL\_write** ::= *ProcOutPort Size Address*



# Simple Statement

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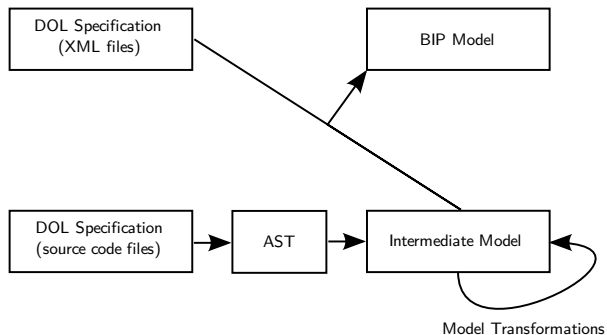
**BIP Models for C Code  
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- 1 Transform code that is not conformant to the restrictions we put on C code into conformant code
- 2 Generate code for initializing variables
- 3 Replace all DOL specificities into something equivalent but with no dependencies to DOL (access to internal data of DOL implementation, ...)

- 1 Collapsing code tree without DOL special functions
- 2 Merging sequential code without DOL special functions
- 3 Transforming `for` loops into simpler `while` loops if possible (i.e. does not contain `continue` statements)

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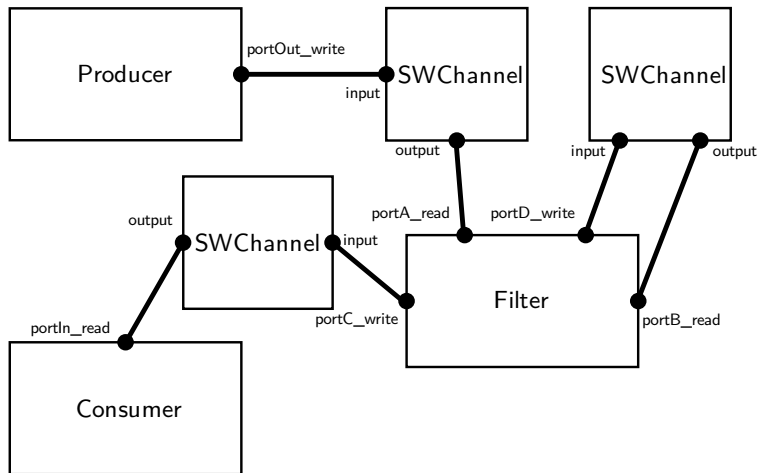
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# Complete Filter Example





# Filter Example: Producer Process

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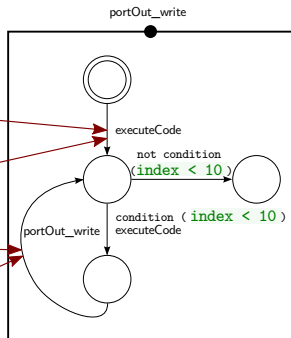
```
int producer_fire(DOLProcess *p)
{
    int index;
    srand(0); //initialize random number generator

    //generate input samples and display them
    printf("producer: samples = { ");

    for (index = 0; index < 10; index++) {
        p->local->sample[index] = (float) getRandomNumber(-9, 9);
        if (index < 9) {
            printf("%+3.1f, ", p->local->sample[index]);
        }
        else {
            printf("%+3.1f }\n", p->local->sample[index]);
        }
    }

    //write samples to output port
    for (index = 0; index < 10; index++) {
        printf("%8s: Write sample[%02d]: %+6.4f\n",
            "producer", index, p->local->sample[index]);
        DOL_write((void*)PORT_OUT, &(p->local->sample[index]),
            sizeof(float), p);
    }

    DOL_detach(p);
    return -1;
}
```



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# Trace of Filter Example

SystemC 2.2.0 --- Nov 3 2008 14:59:36  
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```
producer: samples = { -7.0, +6.0, -6.0, -6.0, +1.0, -1.0, +1.0, +2.0, -7.0, -2.0 }
producer: Write sample[00]: -7.0000
producer: Write sample[01]: +6.0000
producer: Write sample[02]: -6.0000
consumer: Read sample[00]: -7.0000
producer: Write sample[03]: -6.0000
consumer: Read sample[01]: +2.5000
producer: Write sample[04]: +1.0000
consumer: Read sample[02]: -4.7500
producer: Write sample[05]: -1.0000
consumer: Read sample[03]: -8.3750
producer: Write sample[06]: +1.0000
consumer: Read sample[04]: -3.1875
producer: Write sample[07]: +2.0000
consumer: Read sample[05]: -2.5938
producer: Write sample[08]: -7.0000
consumer: Read sample[06]: -0.2969
producer: Write sample[09]: -2.0000
consumer: Read sample[07]: +1.8516
consumer: Read sample[08]: -6.0742
consumer: Read sample[09]: -5.0371
```

```
*****
*   BIP Engine (Version 1.0)   *
*   Verimag, France           *
* (www-verimag.imag.fr/~async/BIP/bip.html)*
*****
```

```
producer: samples = { -7.0, +6.0, -6.0, -6.0, +1.0, -1.0, +1.0, +2.0, -7.0, -2.0 }
producer: Write sample[00]: -7.0000
producer: Write sample[01]: +6.0000
producer: Write sample[02]: -6.0000
consumer: Read sample[00]: -7.0000
producer: Write sample[03]: -6.0000
consumer: Read sample[01]: +2.5000
producer: Write sample[04]: +1.0000
producer: Write sample[05]: -1.0000
consumer: Read sample[02]: -4.7500
consumer: Read sample[03]: -8.3750
producer: Write sample[06]: +1.0000
consumer: Read sample[04]: -3.1875
consumer: Read sample[05]: -2.5938
producer: Write sample[07]: +2.0000
producer: Write sample[08]: -7.0000
consumer: Read sample[06]: -0.2969
producer: Write sample[09]: -2.0000
consumer: Read sample[07]: +1.8516
consumer: Read sample[08]: -6.0742
consumer: Read sample[09]: -5.0371
```

- Fully automatic translation of 7 DOL examples
- Produces a BIP model that is usable for model transformations
- Need to support more complex examples like MPEG decoder
- We want to implement model transformations in order to apply hardware constraints to the model of the software